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# Numerical Simulation Model on Irreversibility of Shock-Wave Process 

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# NUMERICAL SIMULATION MODEL ON IRREVERSIBILITY OF SHOCK-WAVE PROCESS 

by<br>Longhao Huang, B.S.

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# ABSTRACT <br> NUMERICAL SIMULATION MODEL ON IRREVERSIBILITY OF SHOCK-WAVE PROCESS 

Longhao Huang, B.S.

Marquette University, 2013

The objective of this research is to develop a better understanding of the irreversibilities associated with the shock compaction of matter, especially as a result of impact. Due to complex shock processes, experimentation alone cannot fix the material state, since properties such as internal energy, entropy as well as the shock process are not measurable. Thus, in addition to experimentation, analytical and numerical methods are also used to completely characterize the shock process, although they are restricted by underlying constitutive assumptions. Instead of using artificial irreversibility, such as artificial viscosity to simplify and stabilize the numeric shock model, this work will directly incorporate and solve the correct constitutive relations that describe the sources of irreversibility.

Shock wave processes in gas and water are simulated and two equations of state (EOS) are discussed. For a one-dimensional shock wave in gas, results from simulations at two different non-dimensional scales utilizing two different EOS are comparable to the idealized analytical solution and experimental data. Besides, the Mie-Grüneisen (M-G) equation of state, which has been used for solids, is extended to study gas and liquid. The value of Mie-Grüneisen constant, which is a function of atom oscillator frequency and specific volume, is hard to detect from experiment. Based on statistical mechanics, a relationship between the gas Mie-Grüneisen constant and specific heat ratio is derived analytically, which makes Mie-Grüneisen EOS available for gas. The M-G constant is also derived from shock jump condition and Mie-Grüneisen EOS for water and a sensitivity analysis is done based on the simulation result.

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## Chapter 1

## Introduction

### 1.1 Objectives

Research related to shock wave processes has a long history. Compared with elastic deformation process, shock wave process can make irreversible change to the material state. According to material states, constitutive models can be divided into gas, liquid and solid groups, which vary from simple to complex respectively. Due to complex shock processes, there are various kinds of ways to research shock processes. One approach is to design an experiment to directly collect material property data and capture the shock wave profile, such as velocity, density or pressure. Based on experimental data, the shock Hugoniot compression curve can be established, which is used to estimate the shock compressed state. While shock temperature is usually obtained by a theoretical calculations based on the various thermodynamic quantities or shock Hugoniot data available. So experimental methods alone are insufficient to establish the complete equation of state and the preciseness need to be improved. Numeric methods can assist in fixing the complete equation of state. Results from numeric simulations can be compared to specific points on a thermodynamic surface to assess the effectiveness of simulation procedure.

The objective of this research is to develop a better understanding of the irreversibility associated with the shock compaction of matter, especially as a result of impact, based on numerical simulation. In classical numeric formulations the cells size of
the simulation is large compared to the shock thickness, thus the shock is not numerically resolved. As a result, the evolution of irreversibilities within the shock process is not resolved. In order to simplify or stabilize the shock model, artificial irreversibility, such as artificial viscosity, are introduced and applied [1-3]. For one-dimensional shock wave processes in monatomic gas, Navier-Stoke (NS) equations and ideal gas equation of state (EOS) are able to describe the generation of irreversibilities [4]. The use of Navier-Stoke equations makes for a more complete analysis including thermodynamically consistent of temperature [5]. In order to simulate shock interactions that are under resolved, artificial viscosity is included in most simulations in order to dampen-out spurious numeric instabilities. In this work the complete classic Newtonian viscous stress tensor is directly incorporated in the simulation. In order to resolve the gradients required by the Newtonian viscous stress tensor, the very sharp, very thin ( $<1 \mu \mathrm{~m}$ ) shock fronts must be resolved.

Furthermore, shock wave processes in liquids are more complex than those in gases. In order to make one-dimensional Navier-Stoke formulation more robust, additional modifications can be considered, such as non-dimensional scales, different equations of state (EOS), parameter studies and the inclusion of the Newtonian compressibility terms and second viscosity. Specific experimental data and analytical simulation results are to be used to check the accuracy of these simulations. In addition, a sensitivity analysis is presented to analyze the effects of irreversibility in shock wave process.

### 1.2 Methodology

This work compares numerical simulation, analytical simulation and specific experimental data to accomplish stated objectives.

Experiments are usually conducted under Lagrange coordinate, while parameters from Lagrange coordinate are not convenient to use in numeric simulations, so Euler coordinates are used instead. Work starts from assumptions, which are made from experimental design, physics phenomenon and mathematics derivation process. Then, finite difference techniques are used in the discretization based on simplified equations. A second-order central difference is chosen to discretize numerical equations from analytical Navier-Stoke equations, similar to a Crank-Nicolson method. The scheme is programed in FORTRAN.

Two kinds of equations of state are used in these simulations: ideal gas EOS and Mie-Grüneisen EOS. Sub-models of irreversibility come from the full Newtonian fluid stress tensor, where the transport constants for viscosity are assumed constant or follow an experimentally observed trend line, such as power law of viscosity or Maxwell method of viscosity. In order to shorten the simulation time and keep accuracy high, two kinds of non-dimensional scales are used with these equations and variables. This also helps extend the availability of the numerical model from gas to liquid.

## Chapter 2

## Ideal Gas EOS Model

### 2.1 Derivation of Dimensional NS Equations

The following is the general governing Navier-Stokes equations:
Continuity

$$
\begin{equation*}
\frac{\partial}{\partial \mathrm{t}} \rho=-(\nabla \cdot \rho \mathrm{u}) \tag{2.1.1}
\end{equation*}
$$

Motion

$$
\begin{equation*}
\frac{\partial}{\partial \mathrm{t}} \rho \mathrm{u}=-[\nabla \cdot \rho \mathrm{uu}]-\nabla \mathrm{p}-[\nabla \cdot \tau]+\rho \mathrm{g} \tag{2.1.2}
\end{equation*}
$$

Energy

$$
\begin{equation*}
\frac{\partial}{\partial t} \rho(\widehat{K}+\widehat{U})=-(\nabla \cdot \rho(\widehat{K}+\widehat{H}) u)-(\nabla \cdot q)-(\nabla \cdot[\tau \cdot u])+\rho(u \cdot g) \tag{2.1.3}
\end{equation*}
$$

where $\rho$ stands for density, u for the velocity, T for the temperature, $\boldsymbol{\tau}$ for the stress and $P$ is the pressure. In addition the kinetic and internal energy and enthalpy are defined as follows:

$$
\begin{aligned}
\widehat{K} & =\frac{1}{2} u^{2} \text { for the kinetic energy per unit mass, } \\
\widehat{U} & =C_{v} T \text { for the internal energy per unit mass, } \\
\widehat{H} & =\widehat{U}+\frac{p}{\rho} \text { for the enthalpy per unit mass. }
\end{aligned}
$$

The heat flux due to conduction, $q$, is described by Fourier's Law: $q=-\kappa \nabla T$.
Assuming one-dimensional plane flow, $u, T, \rho$ and $p$ are functions of space in the x direction and time t , noted as $\mathrm{u}(\mathrm{x}, \mathrm{t}), \mathrm{T}(\mathrm{x}, \mathrm{t}), \rho(\mathrm{x}, \mathrm{t})$ and $\mathrm{p}(\mathrm{x}, \mathrm{t})$. The velocities in the y and
z drop out of the formulation. The one-dimensional governing equations can be simplified as follows.

Continuity

$$
\begin{equation*}
\frac{\partial}{\partial \mathrm{t}} \rho=-\frac{\partial}{\partial \mathrm{x}} \rho u_{x} \tag{2.1.4}
\end{equation*}
$$

Use u to replace $u_{x}$ and set the momentum $\mathrm{j}=\rho u_{x}$, inserting into equation above, results in

$$
\begin{equation*}
\frac{\partial \rho}{\partial \mathrm{t}}+\frac{\partial \mathrm{j}}{\partial \mathrm{x}}=0 \tag{2.1.5}
\end{equation*}
$$

Motion

$$
\begin{equation*}
\frac{\partial}{\partial \mathrm{t}} \rho \mathrm{u}_{x}=-\frac{\partial \rho \mathrm{u}_{x} u_{x}}{\partial \mathrm{x}}-\frac{\partial \mathrm{p}}{\partial \mathrm{x}}-\frac{\partial \tau_{x x}}{\partial \mathrm{x}} \tag{2.1.6}
\end{equation*}
$$

Rearrange equation (2.1.6) to get

$$
\begin{equation*}
\frac{\partial \mathrm{j}}{\partial \mathrm{t}}+\frac{\partial \mathrm{ju}}{\partial \mathrm{x}}+\frac{\partial \mathrm{p}}{\partial \mathrm{x}}=-\frac{\partial \tau_{x x}}{\partial \mathrm{x}} \tag{2.1.7}
\end{equation*}
$$

Energy

$$
\begin{equation*}
\frac{\partial}{\partial \mathrm{t}} \rho(\widehat{K}+\widehat{U})=-\frac{\partial \rho(\widehat{K}+\widehat{H}) u}{\partial x}-\frac{\partial q_{x}}{\partial \mathrm{x}}-\frac{\partial \tau_{x x} u}{\partial \mathrm{x}} \tag{2.1.8}
\end{equation*}
$$

Where the total energy per unit volume is defined as:

$$
\begin{equation*}
\mathrm{E}=\rho(\widehat{K}+\widehat{U})=K+U \tag{2.1.9}
\end{equation*}
$$

In equation (2.1.9), the U stands for internal energy per unit volume and K stands for kinetic energy per unit volume.

Then, combined with their respective definitions the following equations result:

$$
\begin{align*}
& \mathrm{U}=\rho C_{v} T  \tag{2.1.10}\\
& \mathrm{~K}=\frac{1}{2} \rho u^{2} \tag{2.1.11}
\end{align*}
$$

$$
\begin{equation*}
\mathrm{E}=\frac{1}{2} \rho u^{2}+\rho C_{v} T \tag{2.1.12}
\end{equation*}
$$

The thermodynamic relationships for the specific heats $C_{p}, C_{v}$, and $\gamma$ and R can be written as

$$
\begin{gather*}
\mathrm{R}=C_{p}-C_{v}  \tag{2.1.13}\\
\gamma=\frac{c_{p}}{C_{v}} \tag{2.1.14}
\end{gather*}
$$

where $\gamma$ is the specific heat ratio and,
R is the gas constant.
Combining the equations (2.1.13) and (2.1.14), the following results are

$$
\begin{gather*}
C_{v}=\frac{R}{\gamma-1}  \tag{2.1.15}\\
C_{p}=\frac{R}{\gamma-1}+R=\frac{R \gamma}{\gamma-1} \tag{2.1.16}
\end{gather*}
$$

This can be combined with the ideal gas equation of state

$$
\begin{align*}
\mathrm{p} & =\rho \mathrm{RT}  \tag{2.1.17}\\
\rho C_{v} T & =\frac{\rho R T}{\gamma-1}=\frac{p}{\gamma-1} \tag{2.1.18}
\end{align*}
$$

Total energy can be expressed by $\rho, \gamma$ and $u$, as

$$
\begin{equation*}
\mathrm{E}=\frac{1}{2} \rho u^{2}+\frac{p}{\gamma-1} \tag{2.1.19}
\end{equation*}
$$

The enthalpy is defined in the usual way and can be combined with the kinetic energy for simplification:

$$
\begin{equation*}
\mathrm{H}=\frac{E+p}{\rho}=\frac{\rho(\widehat{K}+\widehat{U})+p}{\rho}=\widehat{K}+\left(\widehat{U}+\frac{p}{\rho}\right)=\widehat{K}+\widehat{H} \tag{2.1.20}
\end{equation*}
$$

The energy evolution equation can be obtained by substituting E and H into energy equation (2.1.8) to get

$$
\begin{equation*}
\frac{\partial}{\partial \mathrm{t}} \mathrm{E}=-\frac{\partial(j H)}{\partial x}-\frac{\partial q_{x}}{\partial \mathrm{x}}-\frac{\partial\left(\tau_{x x} u\right)}{\partial \mathrm{x}} \tag{2.1.21}
\end{equation*}
$$

Finally the energy equation becomes,
Energy

$$
\begin{equation*}
\frac{\partial}{\partial \mathrm{t}} \mathrm{E}+\frac{\partial(j H)}{\partial x}+\frac{\partial q_{x}}{\partial \mathrm{x}}=-\frac{\partial\left(\tau_{x x} u\right)}{\partial \mathrm{x}} \tag{2.1.22}
\end{equation*}
$$

where q is the Fourier Law flux defined as:

$$
\begin{equation*}
\mathrm{q}=q_{x}=-\kappa \frac{\partial T}{\partial x} \tag{2.1.23}
\end{equation*}
$$

Heat conductivity
Some of the transport properties can be combined into dimensionless parameters in order to simplify the governing equations. Since the Prandlt number, Pr, is defined as

$$
\begin{equation*}
\operatorname{Pr}=\frac{C_{p} \eta}{\kappa} \tag{2.1.24}
\end{equation*}
$$

Then rearranging for the heat conduction, k , yields,

$$
\begin{equation*}
\kappa=\frac{C_{p} \eta}{P r} \tag{2.1.25}
\end{equation*}
$$

Insert the expression for the specific heat, $C_{p}$, equation (2.1.16) to get

$$
\begin{equation*}
\kappa=\frac{\gamma R \eta}{(\gamma-1) P r} \tag{2.1.26}
\end{equation*}
$$

The Newtonian stress tensor is defined in equation 2.1.27.

$$
\begin{equation*}
\tau_{x x}=-\eta\left[2 \frac{\partial u_{x}}{\partial x}\right]+\left(\frac{2}{3} \eta-\mu\right)(\nabla \cdot u) \tag{2.1.27}
\end{equation*}
$$

For a monatomic noble gas with low density, where there are no free electrons in the valence shells, one can assume the second viscosity $\mu$ is zero [7]. This is born out by experimental results. As a result, one arrives at the simplified one dimensional stress

$$
\begin{equation*}
\tau_{x x}=-\frac{4}{3} \eta \frac{\partial u}{\partial x} \tag{2.1.28}
\end{equation*}
$$

One should note that equation 2.1.28 retains the compressibility terms from 2.1.27. But it has been simplified greatly. Finally, one should note that in order to resolve this scheme the gradients in equations 2.1.28 and 23 must be resolved.

### 2.2 Non-Dimensional NS Equations - Ideal Gas Scheme

Since the upstream density $\rho_{\infty}$, mean-free path $\lambda$ and sound speed $C_{\infty}$ can be obtained from experiments and the gas constant $R$ is a constant, they are well suited to be used as non-dimensional scales. In addition the ratio of specific heats, $\gamma$ is used to dimensionalize the energy equation. The mean free path for a perfect gas is from G.A.Bird [6]. It can be manipulated to the following form,

$$
\begin{equation*}
\lambda=\frac{4 \eta}{(\rho \sqrt{2 \pi R T} \Omega)} \tag{2.2.1}
\end{equation*}
$$

where, $\Omega$ is a coefficient from mean collision rate of molecule, which is defined as,

$$
\begin{equation*}
\Omega=\frac{5(\alpha+1)(\alpha+2)}{\alpha(7-2 \omega)(5-2 \omega)} \tag{2.2.2}
\end{equation*}
$$

where, $\alpha$ is an exponent in the variable molecular model. When $\alpha=1$, equation (2.2.1) is applicable for hard sphere assumption and $\omega$ is viscosity index, a coefficient related to fluid.

Using scales above mentioned, the following basic dimensionless parameters can be formulated as $\rho=\tilde{\rho} \rho_{\infty}, \mathrm{u}=\tilde{u} C_{\infty}, \mathrm{p}=\tilde{p} \rho_{\infty} C_{\infty}^{2}, \mathrm{x}=\tilde{x} \lambda, \mathrm{t}=\tilde{t} \frac{\lambda}{c_{\infty}}$

Substituting these into the one dimensional governing equations (2.1.5, 2.1.7 and 2.1.22), yields:

$$
\begin{equation*}
\frac{\partial \widetilde{\rho} \rho_{\infty}}{\partial \tilde{\partial} \frac{\lambda}{C_{\infty}}}+\frac{\partial \tilde{\rho} \widetilde{u} \rho_{\infty} C_{\infty}}{\partial \tilde{x} \lambda}=0 \tag{2.2.3}
\end{equation*}
$$

where the momentum flux is defined as:

$$
\begin{equation*}
\mathrm{j}=\rho \mathrm{u}=\tilde{\rho} \tilde{u} \rho_{\infty} C_{\infty} . \tag{2.2.4}
\end{equation*}
$$

Combining these two and factoring yields

$$
\begin{equation*}
\frac{\rho_{\infty} C_{\infty}}{\lambda}\left(\frac{\partial \widetilde{\rho}}{\partial \tilde{t}}+\frac{\partial \widetilde{\rho} \tilde{u}}{\partial \tilde{x}}\right)=0 \tag{2.2.5}
\end{equation*}
$$

which simplifies to

$$
\begin{equation*}
\frac{\partial \widetilde{\rho}}{\partial \tilde{t}}+\frac{\partial \widetilde{\rho} \widetilde{u}}{\partial \tilde{x}}=0 . \tag{2.2.6}
\end{equation*}
$$

The stress can be non-dimensionalized as

$$
\begin{equation*}
\tau_{x x}=-\frac{4}{3} \eta \frac{\partial u}{\partial x}=-\frac{4}{3} \eta \frac{\partial \widetilde{u} c_{\infty}}{\partial \tilde{x} \lambda} \tag{2.2.7}
\end{equation*}
$$

Inserting into the momentum equation yields

$$
\begin{equation*}
\frac{\partial \tilde{\rho} \widetilde{u} \rho_{\infty} C_{\infty}}{\partial \tilde{t} \frac{\lambda}{c_{\infty}}}+\frac{\partial \widetilde{\rho} \tilde{u} \rho_{\infty} C_{\infty} \tilde{u} c_{\infty}}{\partial \tilde{x} \lambda}+\frac{\partial \tilde{p} \rho_{\infty} C_{\infty}^{2}}{\partial \tilde{x} \lambda}=-\frac{\partial \frac{4}{3} \frac{\partial \tilde{u} c_{\infty}}{\partial \tilde{x} \lambda}}{\partial \tilde{x} \lambda} \tag{2.2.8}
\end{equation*}
$$

By collect terms the following equation results,

$$
\begin{align*}
& \frac{\rho_{\infty} C_{\infty}^{2}}{\lambda}\left(\frac{\partial \widetilde{\rho} \tilde{u}}{\partial \tilde{t}}+\frac{\partial \widetilde{\rho} \widetilde{u}^{2}}{\partial \tilde{x}}+\frac{\partial \tilde{p}}{\partial \tilde{x}}\right)=-\frac{4}{3} \eta \frac{C_{\infty}}{\lambda^{2}} \frac{\partial^{2} \widetilde{u}}{\partial \tilde{x}^{2}}  \tag{2.2.9}\\
& \left(\frac{\partial \widetilde{\rho} \widetilde{u}}{\partial \tilde{t}}+\frac{\partial \widetilde{\rho} \widetilde{u}^{2}}{\partial \tilde{x}}+\frac{\partial \tilde{p}}{\partial \tilde{x}}\right)=-\frac{4}{3} \frac{\eta}{\lambda \rho_{\infty} C_{\infty}} \frac{\partial^{2} \widetilde{u}}{\partial \tilde{x}^{2}} \tag{2.2.10}
\end{align*}
$$

The left side of equation (2.2.10) is dimensionless, in order to keep the right side dimensionless, the following requirement is enforced.

$$
\begin{equation*}
\frac{\eta}{\lambda \rho_{\infty} C_{\infty}}=\text { dimensionless } \tag{2.2.11}
\end{equation*}
$$

To get non-dimensional scale for $\eta, \eta=\tilde{\eta}\left(\lambda \rho_{\infty} C_{\infty}\right)$, the momentum equation can be non-dimensionalized as follows:

Momentum

$$
\begin{equation*}
\left(\frac{\partial \tilde{\rho} \tilde{u}}{\partial \tilde{t}}+\frac{\partial \widetilde{\rho} \widetilde{u}^{2}}{\partial \tilde{x}}+\frac{\partial \tilde{p}}{\partial \tilde{x}}\right)=-\frac{4}{3} \tilde{\eta} \frac{\partial^{2} \widetilde{u}}{\partial \tilde{x}^{2}}=-\frac{\partial \tilde{\tau}_{x x}}{\partial \tilde{x}}=\frac{\partial \widetilde{\Pi}_{x x}}{\partial \tilde{x}} \tag{2.2.12}
\end{equation*}
$$

where the stress tensor is

$$
\widetilde{\Pi}_{x x}=-\tilde{\tau}_{x x}
$$

The dimensionless total energy can be written as

$$
\begin{equation*}
\mathrm{E}=\frac{1}{2} \rho u^{2}+\frac{p}{\gamma-1}=\frac{1}{2} \tilde{\rho} \rho_{\infty}\left(\tilde{u} C_{\infty}\right)^{2}+\frac{\tilde{p} \rho_{\infty} C_{\infty}^{2}}{\gamma-1}=\rho_{\infty} C_{\infty}^{2}\left(\frac{1}{2} \tilde{\rho} \tilde{u}^{2}+\frac{\tilde{p}}{\gamma-1}\right)=\rho_{\infty} C_{\infty}^{2} \tilde{E} \tag{2.2.13}
\end{equation*}
$$

where the dimensionless enthalpy is defined as

$$
\begin{equation*}
\mathrm{H}=\frac{E+p}{\rho}=\frac{\rho_{\infty} C_{\infty}^{2} \tilde{E}+\tilde{p} \rho_{\infty} C_{\infty}^{2}}{\widetilde{\rho} \rho_{\infty}}=C_{\infty}^{2} \frac{\tilde{E}+\tilde{p}}{\widetilde{\rho}}=C_{\infty}^{2} \widetilde{H} \tag{2.2.14}
\end{equation*}
$$

From the ideal gas equation of state $p=\rho R T$, the dimensionless temperature can be derived,

$$
\begin{equation*}
\mathrm{T}=\frac{p}{\rho R}=\frac{\tilde{p} \rho_{\infty} C_{\infty}^{2}}{\tilde{\rho} \rho_{\infty} R} \tag{2.2.15}
\end{equation*}
$$

The various thermodynamic variables can be made non-dimensional, which results in

$$
\begin{equation*}
\mathrm{T}=\frac{\gamma \tilde{p} c_{\infty}^{2}}{\gamma \widetilde{\rho} R}=\tilde{T} \frac{C_{\infty}^{2}}{\gamma R} \tag{2.2.16}
\end{equation*}
$$

Further, the heat flux can be non-dimensionalized as

$$
\begin{equation*}
\mathrm{q}=q_{x}=-\kappa \frac{\partial T}{\partial x}=-\kappa \frac{\partial \tilde{T} c_{\infty}^{2}}{\partial \tilde{x} \lambda}=-\kappa \frac{C_{\infty}^{2}}{\lambda \gamma R} \frac{\partial \tilde{T}}{\partial \tilde{x}} \tag{2.2.17}
\end{equation*}
$$

The dimensionless variables $\widetilde{\mathrm{E}}, \widetilde{\mathrm{H}}, \tilde{\mathrm{\jmath}}, \widetilde{\mathrm{~T}}, \tilde{\tau}_{x x}$ and $\tilde{\mathrm{q}}$ with corresponding parameters can be substituted into the energy equation to get

$$
\begin{equation*}
\frac{\partial}{\partial \tilde{t} \frac{\lambda}{c_{\infty}}} \rho_{\infty} C_{\infty}^{2} \tilde{E}+\frac{\partial\left(\widetilde{\rho} \widetilde{u} \rho_{\infty} c_{\infty} C_{\infty}^{2} \widetilde{H}\right)}{\partial \tilde{x} \lambda}+\frac{\partial-\frac{C_{\infty}^{2} \tilde{\lambda}}{\lambda \gamma R} \tilde{q}}{\partial \tilde{x} \lambda}=\frac{\partial\left(\frac{\tilde{3}}{3} \tilde{\eta} \lambda \rho_{\infty} c_{\infty} \frac{\partial \widetilde{u} c_{\infty}}{\partial \tilde{x} \lambda} \widetilde{u} c_{\infty}\right)}{\partial \tilde{x} \lambda} \tag{2.2.18}
\end{equation*}
$$

which reduces to

$$
\begin{equation*}
\frac{\rho_{\infty} C_{\infty}^{3}}{\lambda}\left(\frac{\partial \tilde{E}}{\partial \tilde{t}}+\frac{\partial(\tilde{\jmath} \tilde{H})}{\partial \tilde{x}}\right)+\left(-\kappa \frac{C_{\infty}^{2}}{\lambda^{2} \gamma R}\right) \frac{\partial^{2} \tilde{T}}{\partial \tilde{x}^{2}}=\frac{4 \widetilde{\eta} \rho_{\infty} C_{\infty}^{3}}{3 \lambda} \frac{\partial}{\partial \tilde{x}}\left(\tilde{u} \frac{\partial \widetilde{u}}{\partial \tilde{x}}\right) \tag{2.2.19}
\end{equation*}
$$

Since both sides are multiply by $\frac{\lambda}{\rho_{\infty} C_{\infty}^{3}}$, then the above simplifies to

$$
\begin{equation*}
\frac{\partial \tilde{E}}{\partial \tilde{t}}+\frac{\partial(\tilde{H} \tilde{H})}{\partial \tilde{x}}+\left(\frac{-\kappa}{\rho_{\infty} C_{\infty} \lambda \gamma R}\right) \frac{\partial^{2} \tilde{T}}{\partial \tilde{x}^{2}}=\frac{4 \widetilde{\eta}}{3} \frac{\partial}{\partial \tilde{x}}\left(\tilde{u} \frac{\partial \widetilde{u}}{\partial \tilde{x}}\right) \tag{2.2.20}
\end{equation*}
$$

The right side of this equation is dimensionless, which requires

$$
\begin{equation*}
\frac{-\kappa}{\rho_{\infty} C_{\infty} \lambda \gamma R}=\text { dimensionless } \tag{2.2.21}
\end{equation*}
$$

Assuming the non-dimensional scale for heat conductivity is

$$
\begin{equation*}
\kappa=\tilde{\kappa} \rho_{\infty} C_{\infty} \lambda \gamma R . \tag{2.2.22}
\end{equation*}
$$

Energy equation reduces to

$$
\begin{equation*}
\frac{\partial \tilde{E}}{\partial \tilde{t}}+\frac{\partial(\tilde{(\tilde{H})}}{\partial \tilde{x}}-\tilde{\kappa} \frac{\partial^{2} \tilde{T}}{\partial \tilde{x}^{2}}=-\frac{4}{3} \tilde{\eta}\left[\left(\frac{\partial \tilde{u}}{\partial \tilde{x}}\right)^{2}+\tilde{u} \frac{\partial^{2} \tilde{u}}{\partial \tilde{x}^{2}}\right]=-\frac{\partial\left(\tilde{\tau}_{x x} \tilde{u}\right)}{\partial \tilde{x}}=\frac{\partial\left(\widetilde{\Pi}_{x x} \tilde{u}\right)}{\partial \tilde{x}} \tag{2.2.23}
\end{equation*}
$$

where, $\widetilde{\Pi}_{x x}=-\tilde{\tau}_{x x}$.
So finally on arrives at a consistent dimensionless scheme for gas behavior:

$$
\begin{gathered}
u \sim C_{\infty}, x \sim \lambda, t \sim \frac{\lambda}{C_{\infty}}, \rho \sim \rho_{\infty}, P \sim \rho_{\infty} C_{\infty}^{2}, \\
T \sim \frac{C_{\infty}^{2}}{\gamma R}, \eta \sim \lambda \rho_{\infty} C_{\infty}, \kappa \sim \rho_{\infty} C_{\infty} \lambda \gamma R .
\end{gathered}
$$

### 2.3 Non-Dimensional NS Equations - General Fluid Scheme

The non-dimensional scales used in the previous derivation are for gas simulation. This is because the ideal gas equation of state is explicit in these assumptions. In order to extend the applicability of the non-dimensional scheme to fluids and solids, a set of more
general non-dimensional scales needs to be introduced. As upstream density $\rho_{\infty}$, meanfree path $\lambda$ and sound speed $C_{\infty}$ can be also taken from experiments and analytical calculation in liquid, they can be used for this purpose. To get more general the gas constant R can be replaced by the specific heat Cv . This eliminates the need for the gas specific heat ratio $\gamma$.

Thus the more general non-dimensional scales are as following:
Fundamental scales

$$
\rho=\tilde{\rho} \rho_{\infty}, \mathrm{u}=\tilde{u} C_{\infty}, \mathrm{p}=\tilde{p} \rho_{\infty} C_{\infty}^{2}, \mathrm{x}=\tilde{x} \lambda, \mathrm{t}=\tilde{t} \frac{\lambda}{c_{\infty}},
$$

where, $C_{\infty}$ is no longer local sound speed, but bulk sound speed.
The secondary scales can be expressed as follows:

$$
\eta=\tilde{\eta}\left(\lambda \rho_{\infty} C_{\infty}\right), \mathrm{T}=\tilde{T} \frac{c_{\infty}^{2}}{c_{v}}, \mathrm{k}=\tilde{k}\left(C_{v} \lambda \rho_{\infty} C_{\infty}\right), \mathrm{q}=\tilde{q}\left(\rho_{\infty} C_{\infty}^{3}\right)
$$

During the dimensionless process, the main differences between the gas and the more general fluid/solid dimensionless process is in terms related to temperature. The temperature does not directly appear in the continuity equation and momentum equation. However they are loosely coupled through the transport properties. So the dimensionless forms of these two equations are the same as equation (2.2.6) and (2.2.12).

In order to keep the same unit of heat conductivity, a non-dimensional scale of heat conductivity is introduced, $C_{v} \lambda \rho_{\infty} C_{\infty}$, instead of $\rho_{\infty} C_{\infty} \lambda \gamma R$.

Thus the energy equation is

$$
\begin{equation*}
\frac{\partial \tilde{E}}{\partial \tilde{t}} \frac{\rho_{\infty} C_{\infty}^{3}}{\lambda}+\frac{\partial\left((\tilde{\rho} \tilde{u} \widetilde{H}) \rho_{\infty} C_{\infty}^{3}\right)}{\partial \tilde{x} \lambda}+\frac{\partial \tilde{q} \rho_{\infty} C_{\infty}^{3}}{\partial \tilde{x} \lambda}=\frac{\partial\left(\frac{4}{3} \widetilde{\eta} \lambda \rho_{\infty} C_{\infty} \frac{\left.\partial \tilde{u} C_{\infty} \widetilde{u} C_{\infty}\right)}{\partial \tilde{x} \lambda}\right.}{\partial \tilde{x} \lambda} \tag{2.3.1}
\end{equation*}
$$

which simplifies to,

$$
\begin{equation*}
\frac{\partial \tilde{E}}{\partial \tilde{t}}+\frac{\partial(\tilde{\jmath} \widetilde{H})}{\partial \tilde{x}}+\frac{\partial \tilde{q}}{\partial \tilde{x}}=\frac{4}{3} \frac{\partial\left(\tilde{\eta} \frac{\partial \tilde{u}}{\partial \tilde{u})}\right.}{\partial \tilde{x}}=\frac{4}{3} \frac{\partial\left(\widetilde{\Pi}_{x x} \widetilde{u}\right)}{\partial \tilde{x}} \tag{2.3.2}
\end{equation*}
$$

where, $\widetilde{\Pi}_{x x}=-\tilde{\tau}_{x x}$.

### 2.4 Gas Viscosity Sub-Models

Viscosity $\eta$ and heat conductivity $\kappa$ are functions of temperature. Four models of viscosity have been investigated in the work, constant viscosity model, power law model, Maxwell model [6] and Chapman-Enskog model [7].

## Power Law Model

The power law viscous model is derived from simple observation of experimental measurements that illustrate that viscosity varies with respect to temperature. Experimental data is found to fit a power law form of the following:

$$
\begin{equation*}
\eta=\eta_{\infty}\left(\frac{T}{T_{\infty}}\right)^{\omega} \tag{2.4.1}
\end{equation*}
$$

where, $\eta_{\infty}$ is upstream viscosity, $T_{\infty}$ is upstream temperature, and $\omega$ is viscosity index based on the data in Chapman and Cowling (1970) [6].

Equation (2.4.1) can be converted into dimensionless form

$$
\begin{equation*}
\tilde{\eta}=\tilde{\eta}_{\infty}\left(\frac{\tilde{T}}{\tilde{T}_{\infty}}\right)^{\omega} \tag{2.4.2}
\end{equation*}
$$

Since the dimensionless upstream boundary condition for temperature is $\widetilde{T}_{\infty}=1.0$, the viscosity simples to

$$
\begin{equation*}
\tilde{\eta}=\tilde{\eta}_{\infty}(\tilde{T})^{\omega} \tag{2.4.3}
\end{equation*}
$$

## Maxwell model

The Maxwell model is an analytic viscosity model derived from ridged body particle behavior and a Boltzman velocity distribution [7]. The result is

$$
\begin{equation*}
\eta=\frac{2}{3} \frac{\sqrt{m k T / \pi}}{\pi d^{2}} \tag{2.4.4}
\end{equation*}
$$

where, $m$ is molecular mass, $k$ is Boltzmann's constant, $d$ is the diameter of gas molecule, such as argon, $k T=\tilde{k} \tilde{T} \rho_{\infty} \lambda^{3} C_{\infty}^{2}, m=\tilde{m} \rho_{\infty} \lambda^{3}, d=\tilde{d} \lambda$.

Inserting and simplifying yields

$$
\begin{equation*}
\tilde{\eta}=\frac{2}{3 \pi \tilde{d}^{2}} \sqrt{\frac{\tilde{m} \tilde{k} \tilde{T}}{\pi}} \tag{2.4.5}
\end{equation*}
$$

## Chapman-Enskog Model

The Chapman-Enskog model is based a semi-theoretical assumption by Chapman and Enskog. It's an extension of the rigid ball/Botzman distribution model of Maxwell that includes weak attractive forces. The resulting equation is

$$
\begin{equation*}
\eta=\frac{5}{16} \frac{\sqrt{\pi m k T}}{\pi \sigma^{2} \Omega_{u}} \tag{2.4.6}
\end{equation*}
$$

where, $m$ is molecular mass, $k$ is Boltzmann's constant, $\sigma$ is the diameter of gas molecule, $\Omega_{u}$ is dimensionless collision integrals, which can be derived from the trend line as a function of $\mathrm{kT} / \varepsilon$, which is an empirical parameter.

Inserting dimensional properties, $m=\tilde{m} \rho_{\infty} \lambda^{3}, \sigma=\tilde{\sigma} \lambda$, and $k T=\tilde{k} \tilde{T} \rho_{\infty} \lambda^{3} C_{\infty}^{2}$ into equation (2.4.6) one arrives at the following simplified result:

$$
\begin{equation*}
\tilde{\eta}=\frac{5}{16 \Omega_{u} \widetilde{\sigma}^{2}} \sqrt{\frac{\tilde{m} \tilde{k} \tilde{T}}{\pi}} \tag{2.4.7}
\end{equation*}
$$

With regard to the non-dimensional process, these viscosity models are not affected by the choice of non-dimensional scales.

### 2.5 Discretization

A second order, central difference, finite difference method is used to discretize the analytic equations presented above. The resulting numerical equations and schemes are similar to a Crank-Nicolson method, where parameters with even subscript are face grids and node grids are marked by odd subscripts. This effectively stagers the space grid and stabilizes the solution integration.

The following finite difference scheme is used:

## Continuity

Analytical Form,

$$
\begin{equation*}
\frac{\partial \widetilde{\rho}}{\partial \tilde{t}}+\frac{\partial \widetilde{\rho} \widetilde{u}}{\partial \tilde{x}}=0 \tag{2.5.1}
\end{equation*}
$$

Finite difference form,

$$
\begin{equation*}
\left(\frac{\partial \widetilde{\rho}}{\partial \tilde{t}}\right)_{i}^{n}+\frac{\partial \tilde{\jmath}(i)}{\partial \tilde{x}}=0 \tag{2.5.2}
\end{equation*}
$$

The subscript i is corresponding to space change and superscript n is for time change.

The discrete form can be written as follows:

$$
\begin{equation*}
\frac{\widetilde{\rho}^{n+1}(i)-\widetilde{\rho}^{n}(i)}{\Delta \tilde{t}}+\frac{\tilde{\jmath}(i+1)-\tilde{\jmath}(i-1)}{2 \Delta \tilde{x}}=0 \tag{2.5.3}
\end{equation*}
$$

The hat (or carrot) is used to denote time change,

$$
\begin{equation*}
\tilde{\rho}^{n+1}(i)=\hat{\rho}(i) \tag{2.5.4}
\end{equation*}
$$

therefore the forward time density can be expressed as:

$$
\begin{equation*}
\hat{p}(i)=\tilde{p}(i)-\frac{\Delta \tilde{t}}{2 \Delta \tilde{x}}[\tilde{\jmath}(i+1)-\tilde{\jmath}(i-1)] \tag{2.5.5}
\end{equation*}
$$

## Momentum

The generalized non-dimensional differential form of the energy equation can be written as,

$$
\begin{equation*}
\left(\frac{\partial \widetilde{\rho} \tilde{u}}{\partial \tilde{t}}+\frac{\partial \tilde{\rho} \tilde{u}^{2}}{\partial \tilde{x}}+\frac{\partial \tilde{p}}{\partial \tilde{x}} \tilde{x}\right)=-\frac{4}{3} \tilde{\eta} \frac{\partial^{2} \tilde{u}}{\partial \tilde{x}^{2}} \tag{2.5.6}
\end{equation*}
$$

The finite difference form is,

$$
\begin{equation*}
\left(\frac{\partial \tilde{J}}{\partial \tilde{t}}{ }_{i}^{n}+\frac{\partial \tilde{\jmath} \tilde{u}}{\partial \tilde{x}}+\frac{\partial \tilde{p}}{\partial \tilde{x}}=-\frac{\partial \tilde{\tau}_{x x}}{\partial \tilde{\mathrm{x}}}=\frac{\partial \widetilde{\Pi}_{x x}}{\partial \tilde{\mathrm{x}}}\right. \tag{2.5.7}
\end{equation*}
$$

where the discrete form can be written as:

$$
\begin{equation*}
\frac{\tilde{\tilde{j}}^{n+1}(i)-\tilde{\jmath}^{n}(i)}{\Delta \tilde{t}}=\frac{\widetilde{\Pi}_{x x}{ }^{n+1}(i+1)-\widetilde{\Pi}_{x x}{ }^{n}(i-1)}{2 \Delta \tilde{x}}-\frac{\tilde{p}(i+1)-\tilde{p}(i-1)}{2 \Delta \tilde{x}}-\frac{\tilde{\jmath}(i+1)-\tilde{\jmath}(i-1)}{2 \Delta \tilde{x}} \tag{2.5.8}
\end{equation*}
$$

Again, the hat notation denotes time change

$$
\begin{equation*}
\tilde{\jmath}^{n+1}(i)=\hat{\jmath}(i) \tag{2.5.9}
\end{equation*}
$$

Thus the momentum can be expressed as:

$$
\begin{equation*}
\hat{\jmath}(i)=\tilde{\jmath}(i)+\frac{\Delta \tilde{[ }\left[\widetilde{\Pi}_{x x}{ }^{n+1}(i+1)-\widetilde{\Pi}_{x x}{ }^{n}(i-1)-\tilde{p}(i+1)+\tilde{p}(i-1)-\tilde{\jmath}(i+1)+\tilde{\jmath}(i-1)\right]}{2 \Delta \tilde{x}} \tag{2.5.10}
\end{equation*}
$$

where the viscous terms can be written as:

$$
\begin{equation*}
\Pi_{x x}=\frac{4}{3} \tilde{\eta}(i) \frac{\partial \widetilde{u}}{\partial \tilde{x}}=\frac{4}{3} \frac{\tilde{\eta}(i+1)+\tilde{\eta}(i-1)}{2} \frac{\tilde{u}(\mathrm{i}+1)-\widetilde{u}(\mathrm{i}-1)}{2 \Delta \tilde{x}} \tag{2.5.11}
\end{equation*}
$$

## Energy

The analytical form of the energy equation is:

$$
\begin{equation*}
\frac{\partial \tilde{E}}{\partial \tilde{t}}+\frac{\partial(\tilde{\jmath} \tilde{H})}{\partial \tilde{x}}-\tilde{\kappa} \frac{\partial^{2} \tilde{T}}{\partial \tilde{x}^{2}}=-\frac{3}{4} \tilde{\eta}\left[\left(\frac{\partial \widetilde{u}}{\partial \tilde{x}}\right)^{2}+\tilde{u} \frac{\partial^{2} \tilde{u}}{\partial \tilde{x}^{2}}\right]=\frac{\partial\left(\widetilde{\Pi}_{x x} \tilde{u}\right)}{\partial \tilde{\mathrm{x}}} \tag{2.5.12}
\end{equation*}
$$

The finite difference form reduces to:

$$
\begin{equation*}
\left(\frac{\partial \tilde{E}}{\partial \tilde{t}}\right)_{i}^{n}=-\frac{\partial(\tilde{(\tilde{H})}}{\partial \tilde{x}}+\tilde{\kappa} \frac{\partial^{2} \tilde{T}}{\partial \tilde{x}^{2}}+\frac{\partial\left(\widetilde{\Pi}_{x x} \tilde{u}\right)}{\partial \tilde{\mathrm{x}}} \tag{2.5.13}
\end{equation*}
$$

where the discrete form is:

$$
\begin{gather*}
\frac{\tilde{E}^{n+1}(i)-\tilde{E}^{n}(i)}{\Delta \tilde{t}}=\frac{\widetilde{\Pi}_{x x}(i+1) \tilde{u}(i+1)-\widetilde{\Pi}_{x x}(i-1) \tilde{u}(i-1)}{2 \Delta \tilde{x}} \\
-\frac{\tilde{\jmath}(i+1) \widetilde{H}(i+1)-\tilde{\jmath}(i-1) \widetilde{H}(i-1)}{2 \Delta \tilde{x}}-\frac{\tilde{q}(i+1)-\tilde{q}(i-1)}{2 \Delta \tilde{x}}  \tag{2.5.14}\\
\tilde{E}^{n+1}(i)=\widehat{E}(i) \tag{2.5.15}
\end{gather*}
$$

Discrete forms for velocity $\hat{u}(i)$ and $\hat{\rho}(i)$ have been derived from the NavierStokes (NS) equation. Furthermore, pressure $\hat{p}(i)$ and temperature $\hat{T}(i)$ need to be determined. Constitutive equations can be applied to solve for these two variables. Because $\hat{E}(i)$ is known by definition,

$$
\begin{equation*}
\widehat{\mathrm{E}}(\mathrm{i})=\frac{1}{2} \hat{\rho}(i) \cdot \hat{u}^{2}(i)+\frac{\hat{p}(i)}{\gamma-1} \tag{2.5.15}
\end{equation*}
$$

then, $\hat{p}(i)$ can be written as:

$$
\begin{equation*}
\hat{p}(i)=(\gamma-1)\left[\widehat{\mathrm{E}}(\mathrm{i})-\frac{1}{2} \hat{\rho}(i) \cdot \hat{u}^{2}(i)\right] \tag{2.5.16}
\end{equation*}
$$

According to the ideal gas equation of state,

$$
\begin{equation*}
\hat{p}(i)=\hat{\rho}(i) R \widehat{T}(i) \tag{2.5.17}
\end{equation*}
$$

Since temperature can be written as:

$$
\begin{equation*}
\mathrm{T}=\widetilde{T} \frac{C_{\infty}^{2}}{\gamma R} \tag{2.5.18}
\end{equation*}
$$

$\widehat{T}$ (i) can be resolved from equation 2.5 .17 and 18 , as:

$$
\begin{equation*}
\widehat{T}(\mathrm{i})=\frac{\gamma \hat{p}(i)}{\widehat{\rho}(i)} \tag{2.5.19}
\end{equation*}
$$

## Heat flux

The heat flux is defined by Fourier Law as:

$$
\begin{equation*}
\mathrm{q}=-\kappa \frac{\partial T}{\partial x} \tag{2.5.20}
\end{equation*}
$$

Heat conductivity can be written in a function related to viscosity and gas parameters, $\gamma, \mathrm{R}$ and Prandtl number Pr , as:

$$
\begin{equation*}
\kappa=\frac{\gamma R \eta}{(\gamma-1) P r} \tag{2.5.21}
\end{equation*}
$$

Inserting this into equation 2.5.20, the following expression for the heat flux can be written:

$$
\begin{equation*}
\tilde{\mathrm{q}}(\mathrm{i})=-\frac{\gamma R \eta}{(\gamma-1) P r} \frac{\partial T(i)}{\partial x}=-\frac{1}{(\gamma-1) P r} \frac{\widetilde{\eta}(i+1)+\widetilde{\eta}(i-1)}{2} \frac{\tilde{T}(i+1)-\widetilde{T}(i-1)}{2 \Delta \tilde{x}} \tag{2.5.22}
\end{equation*}
$$

Face grids are assigned the average of adjoining node values [4], as:
Mass flux,

$$
\begin{equation*}
j(i)=\frac{j(i+1)+j(i-1)}{2} \tag{2.5.23}
\end{equation*}
$$

Velocity,

$$
\begin{equation*}
u(i)=\frac{u(i+1)+u(i-1)}{2} \tag{2.5.24}
\end{equation*}
$$

Pressure,

$$
\begin{equation*}
p(i)=\frac{p(i+1)+p(i-1)}{2} \tag{2.5.25}
\end{equation*}
$$

Density,

$$
\begin{equation*}
\rho(i)=\frac{\rho(i+1)+\rho(i-1)}{2} \tag{2.5.26}
\end{equation*}
$$

Total Energy,

$$
\begin{equation*}
E(i)=\frac{E(i+1)+E(i-1)}{2} \tag{2.5.27}
\end{equation*}
$$

Enthalpy,

$$
\begin{equation*}
H(i)=\frac{E(i)+P(i)}{\rho(i)} \tag{2.5.28}
\end{equation*}
$$

i are odd numbers for faces and even numbers for nodes as following:


Figure 2.5.1 Numerical Scheme

### 2.6 Boundary Condition (B.C.)

The left hand side boundary condition can be determined by measurements and analytical calculation or fixed under specific conditions that are reasonable. While the right hand side boundary conditions are more difficult to determine, They depend on a jump relation which include material specific behavior. Two kinds of methods are used to determine right hand side B.C. of shock wave in gas medium. One is the normal shock equations, which is restricted to ideal gas behavior; the other is Rankine-Hugoniot jump condition equations, which is available both for both gas and liquid medium.

### 2.6.1 Normal Shock Equations

The ideal gas specific shock jump equations are as following:
Pre-shock Mach number is:

$$
\begin{equation*}
M a_{1}=\frac{u_{1}}{\sqrt{\gamma R T_{1}}} \tag{2.6.1.1}
\end{equation*}
$$

Post-shock Mach number is:

$$
\begin{equation*}
M a_{2}=\sqrt{\frac{M a_{1}^{2}+\frac{2}{\gamma-1}}{\frac{2 M a_{1}^{2} \gamma}{\gamma-1}-1}} \tag{2.6.1.2}
\end{equation*}
$$

Pressure ratio is:

$$
\begin{equation*}
\frac{P_{2}}{P_{1}}=\frac{1+\gamma M a_{1}^{2}}{1+\gamma M a_{2}^{2}} \tag{2.6.1.3}
\end{equation*}
$$

Temperature ratio is:

$$
\begin{equation*}
\frac{T_{2}}{T_{1}}=\frac{1+\frac{(\gamma-1) M a_{1}^{2}}{2}}{1+\frac{(\gamma-1) M a_{2}^{2}}{2}} \tag{2.6.1.4}
\end{equation*}
$$

Density ratio is:

$$
\begin{equation*}
\frac{\rho_{2}}{\rho_{1}}=\frac{P_{2} T_{1}}{P_{1} T_{2}} \tag{2.6.1.5}
\end{equation*}
$$

Usually, it is more convenient to present the boundary conditions as ratios across shock wave conditions. So, dimensionless parameters are often specified and the right hand side B.C. is determined from the ratios. In this thesis state 1 stands for pre-shock condition, state 2 stands for post-shock condition.

### 2.6.2 Rankine-Hugoniot Equations

In order to specify boundary conditions for non-ideal gas behavior with the context of this numerical model, the following Rankine-Hugoniot Equations are incorporated, which are more general than normal shock equations.

Continuity

$$
\begin{equation*}
\rho_{2} U_{2}=\rho_{1} U_{1} \tag{2.6.1.5}
\end{equation*}
$$

Momentum

$$
\begin{equation*}
\rho_{2} U_{2}^{2}+P_{2}=\rho_{1} U_{1}^{2}+P_{1} \tag{2.6.1.6}
\end{equation*}
$$

Energy

$$
\begin{equation*}
\rho_{2} U_{2}\left(e_{2}+\frac{U_{2}^{2}}{2}+\frac{P_{2}}{\rho_{2}}\right)=\rho_{1} U_{1}\left(e_{1}+\frac{U_{1}^{2}}{2}+\frac{P_{1}}{\rho_{1}}\right) \tag{2.6.1.7}
\end{equation*}
$$

### 2.7 Entropy Calculation Equations

In order to specify the reliability of the numerical simulation, the values of entropy change from theoretical calculation and numerical simulation are compared.

Theoretical entropy change:

$$
\begin{equation*}
S_{2}-S_{1}=C_{v} \cdot \ln \left(\frac{T_{2}}{T_{1}}\right)+R \cdot \ln \left(\frac{\rho_{1}}{\rho_{2}}\right) \tag{2.7.1}
\end{equation*}
$$

Integrate form of entropy change is used in numerical simulation:

$$
\begin{equation*}
S_{2}-S_{1}=\frac{1}{\dot{m}}\left(\int \frac{\tau}{T} \frac{d v}{d x} d x-\int \frac{1}{T} \frac{d q}{d x} d x\right) \tag{2.7.2}
\end{equation*}
$$

Where, $\dot{m}$ is mass flow rate, $\tau$ is shear force, $q$ is heat flux.

### 2.8 Theoretical Solution for Gas

Theoretical solution is set up on one-dimensional compressible flow in a stationary shock wave condition and assumes steady flow with constant viscosity, heat conductivity and specific heat. Second viscosity is neglected for low density gas. [7]

Subscript 1 is corresponding to upstream conditions. The dimensionless velocity distribution equation $\phi(\xi)$ can be written as:

$$
\begin{equation*}
\frac{1-\phi}{(\phi-\alpha)^{\alpha}}=\exp \left[\beta M a_{1}(1-\alpha)\left(\xi-\xi_{0}\right)\right] \quad(\alpha<\phi<1) \tag{2.8.1}
\end{equation*}
$$

where, $\phi$ is dimensionless velocity, $\phi=\frac{v_{x}}{v_{1}} ; \xi$ is dimensionless coordinate, $\xi=\frac{x}{\lambda}$;
$M a_{1}$ is the Mach number at the upstream condition,

$$
\begin{equation*}
M a_{1}=\frac{v_{1}}{\sqrt{\gamma R T_{1} / M}} ; \tag{2.8.2}
\end{equation*}
$$

$\alpha$ and $\beta$ are group terms as follows:

$$
\begin{equation*}
\alpha=\frac{\gamma-1}{\gamma+1}+\frac{2}{\gamma+1} \frac{1}{M a_{1}{ }^{2}}, \tag{2.8.3}
\end{equation*}
$$

$$
\begin{equation*}
\beta=\frac{9}{8}(\gamma+1) \sqrt{\pi / 8 \gamma} \tag{2.8.4}
\end{equation*}
$$

The reference mean free path $\lambda$ is defined as:

$$
\begin{equation*}
\lambda=\frac{3 u_{1}}{\rho_{1}} \sqrt{\frac{\pi M}{8 R T_{1}}} \tag{2.8.5}
\end{equation*}
$$

### 2.9 Mie-Grüneisen EOS

Comparing with section 2.3, this section uses Mie-Grüneisen EOS instead of ideal gas EOS to find the relationship between these two kinds of EOS [8-9].

Mie-Grüneisen equation of state (M-G EOS)

$$
\begin{equation*}
P-P_{0}=\frac{\gamma}{v}\left(\varepsilon-\varepsilon_{0}\right) \tag{2.9.1}
\end{equation*}
$$

where, $P$ is the pressure, $\varepsilon$ is the internal energy, $P_{0}$ and $\varepsilon_{0}$ are pressure and internal energy at zero-kelvin states, they can be calculated out by polynomial equations, $\gamma$ is the Mie-Grüneisen parameter, $v$ is the specific volume.

Zero-kelvin curve can be evaluated using the Hugoniot as a reference curve,

$$
\begin{equation*}
P_{H}-P_{0}=\frac{\gamma}{v}\left(\varepsilon_{H}-\varepsilon_{0}\right) \tag{2.9.2}
\end{equation*}
$$

With equation of state of material,

$$
\begin{equation*}
U_{s}=c+s U_{p} \tag{2.9.3}
\end{equation*}
$$

Hugoniot pressure can be expressed,

$$
\begin{equation*}
P_{H}=\frac{\rho_{0} c^{2} x}{(1-s x)^{2}} \tag{2.9.4}
\end{equation*}
$$

where, $x=1-\frac{V}{V_{0}}=1-\frac{\rho_{0}}{\rho}$.
Corresponding internal energy is

$$
\begin{equation*}
\varepsilon_{H}=\frac{P_{H} v_{0} x}{2} \tag{2.9.5}
\end{equation*}
$$

A good approximation (2.9.6) from experiments is also used during derivation process.

$$
\begin{equation*}
\frac{\gamma}{v}=\frac{\gamma_{0}}{v_{0}}=\text { Contant } \tag{2.9.6}
\end{equation*}
$$

Plug above equations into equation (2.9.2) to get

$$
\begin{equation*}
\frac{\gamma_{0}}{v_{0}} \varepsilon_{0}+\frac{\partial \varepsilon_{0}}{\partial v}+\frac{\rho_{0} c^{2} x}{(1-s x)^{2}}\left(1-\frac{\gamma_{0}}{2} x\right)=0 \tag{2.9.7}
\end{equation*}
$$

$4^{\text {th }}$ order polynomial equation of internal energy $\varepsilon_{0}$ is written as:

$$
\begin{equation*}
\varepsilon_{0}=\varepsilon_{00}+\varepsilon_{01} x+\varepsilon_{02} x^{2}+\varepsilon_{03} x^{3}+\varepsilon_{04} x^{4} \tag{2.9.8}
\end{equation*}
$$

$4^{\text {th }}$ order polynomial equation of $P_{0}$ is:

$$
\begin{equation*}
P_{0}=-\frac{\partial \varepsilon_{0}}{\partial v}=\rho_{0}\left(\varepsilon_{01}+2 \varepsilon_{02} x+3 \varepsilon_{03} x^{2}+4 \varepsilon_{04} x^{3}\right) \tag{2.9.9}
\end{equation*}
$$

$\varepsilon_{0}$ and $P_{0}$ in equation (2.9.7) can be replaced with equation (2.9.8) and (2.9.9).
Form any strain value, equation (2.9.7) is established generally. So coefficients can be determined.

$$
\begin{align*}
& \varepsilon_{01}=\gamma_{0} \varepsilon_{00}  \tag{2.9.10}\\
& \varepsilon_{02}=\frac{1}{2}\left(c^{2}+\gamma_{0}^{2} \varepsilon_{00}\right)  \tag{2.9.11}\\
& \varepsilon_{03}=\frac{1}{6}\left(4 s c^{2}+\gamma_{0}^{3} \varepsilon_{00}\right)  \tag{2.9.12}\\
& \varepsilon_{04}=\frac{1}{24}\left(18 s^{2} c^{2}-2 \gamma_{0} s c^{2}+\gamma_{0}^{4} \varepsilon_{00}\right), \tag{2.9.13}
\end{align*}
$$

Plug these coefficients from equation (2.9.10) to (2.9.13) into equation (2.9.7) and neglect 4th order term; M-G EOS is expanded as following,

$$
\begin{equation*}
P=\rho_{0} c^{2}\left[x+\left(2 s-\frac{\gamma_{0}}{2}\right) x^{2}+s\left(3 s-\gamma_{0}\right) x^{3}\right]+\frac{\gamma_{0} \varepsilon}{v_{0}} \tag{2.9.14}
\end{equation*}
$$

Its corresponding dimensionless form is

$$
\begin{equation*}
\tilde{P}=\left[x+\left(2 s-\frac{\gamma_{0}}{2}\right) x^{2}+s\left(3 s-\gamma_{0}\right) x^{3}\right]+\gamma_{0} \tilde{\varepsilon} \tag{2.9.15}
\end{equation*}
$$

During shock wave transmitting, corresponding to iteration in numerical simulation, density, pressure and internal energy can be solved by NS equations and M-G EOS. Temperature is derived from equation (2.9.16)

$$
\begin{equation*}
\varepsilon-\varepsilon_{0}=\int_{T_{0}}^{T} C v d T \tag{2.9.16}
\end{equation*}
$$

For constant Cv , specific heat at constant volume, temperature T is

$$
\begin{equation*}
T=T_{0}+\frac{\varepsilon-\varepsilon_{0}}{C v} \tag{2.9.17}
\end{equation*}
$$

Its dimensionless form is:

$$
\begin{equation*}
\tilde{T}=\widetilde{T_{0}}+\tilde{\varepsilon}-\widetilde{\varepsilon_{0}} \tag{2.9.18}
\end{equation*}
$$

Actually, Cv is a function related to temperature, which is discussed in chapter 4 sensitive analysis.

### 2.10 Mie-Grüneisen Parameter - Gas

### 2.10.1 General Derivation

M-G EOS

$$
\begin{equation*}
P-P_{0}=\frac{\gamma}{v}\left(\varepsilon-\varepsilon_{0}\right) \tag{2.10.1.1}
\end{equation*}
$$

where, $P_{0}, \varepsilon_{0}$ and $\frac{\gamma}{v}$ are constant.
Differential both sides of equation (2.10.1.1) to get

$$
\begin{equation*}
d P=\frac{\gamma}{v} d \varepsilon \tag{2.10.1.2}
\end{equation*}
$$

Rearrange equation (2.10.1.2), an equation for $\gamma$ is derived,

$$
\begin{equation*}
\gamma=v \frac{d P}{d \varepsilon} \tag{2.10.1.3}
\end{equation*}
$$

For gas, relation between pressure and internal energy is $\varepsilon=\frac{P}{\rho(\gamma-1)}$, so $\frac{d P}{d \varepsilon}=$ $\rho(\gamma-1)$,
where, $\gamma$ is specific heat ratio. In order to distinguish M-G parameter $\gamma$ with specific heat ratio $\gamma . \gamma_{h}$ is used to replace specific heat ratio.

A relation between M-G parameter $\gamma$ and specific heat ratio $\gamma_{h}$ is derived.

$$
\begin{equation*}
\gamma=\gamma_{h}-1 \tag{2.10.1.4}
\end{equation*}
$$

### 2.10.2 Reference State

As known from equation (2.9.8) and (2.9.9), for reference state, $\mathrm{x}=0$,

$$
\begin{gather*}
\varepsilon_{0}=\varepsilon_{00}  \tag{2.10.2.1}\\
P_{0}=\rho_{0} \varepsilon_{01} \tag{2.10.2.2}
\end{gather*}
$$

Solving these two equations above with $\varepsilon_{01}=\gamma_{0} \varepsilon_{00}$ to get

$$
\begin{equation*}
\varepsilon_{0}=\frac{P_{0}}{\rho_{0} \gamma_{0}} \tag{2.10.2.3}
\end{equation*}
$$

Compare with ideal gas internal energy equation $\varepsilon_{0}=\frac{P_{0}}{\rho_{0}(\gamma-1)}, \gamma_{0}$ can be determined.

$$
\begin{equation*}
\gamma_{0}=(\gamma-1) \tag{2.10.2.4}
\end{equation*}
$$

From above derivation, M-G $\gamma$ is constant for gas. The physical meaning of M-G $\gamma$ is the resistance of compression at certain temperature, which means the resistance of compression for low density gas is not sensitive to temperature change.

### 2.10.3 Eulerian and Lagrangian Referential

In reality, gas can transmit in wind tunnel in several Mach number, while shockwave transmits though liquid phase materials and experiments are usually conducted in Lagrangian referential. This model set meshes fixed in space, in order to extend the availability of this model. Lagrangian referential is to be transferred to Eulerian referential. The relationship between particle velocity and shock wave velocity are as following:

$$
\begin{align*}
& U_{1}=U_{s}-U_{p 1}  \tag{2.10.3.1}\\
& U_{2}=U_{s}-U_{p 2} \tag{2.10.3.2}
\end{align*}
$$

where,
$U_{1}$ and $U_{2}$ are material pre-shock and post-shock velocities in Lagrangian referential,
$U_{s}$ is shock wave velocity, $U_{s}=s U_{p 2}+c$,
$U_{p 1}$ is pre-shock particle velocity. $U_{p 1}=0$, for stationary materials,
$U_{p 2}$ is post-shock particle velocity.
This model mainly simulates first shock caused by impact. For stationary materials, there is only one particle velocity $U_{p 1}=0, U_{p 2}=U_{p}$. Equation (2.10.3.1) and equation (2.10.3.2) are simplified,

$$
\begin{gather*}
U_{1}=U_{s}  \tag{2.10.3.3}\\
U_{2}=U_{s}-U_{p} \tag{2.10.3.4}
\end{gather*}
$$

Solving above linear equation system to get

$$
\begin{equation*}
U_{p}=U_{1}-U_{2} \tag{2.10.3.5}
\end{equation*}
$$

### 2.10.4 Extended Equation of State of Material (Us-Up curve)

Equation of state of material is usually used for liquid and solid. There is no accurate reference for gas, while coefficients of S and C for gas can be solved by analytical way. From chapter 2.6, boundary conditions of shock wave are determined. There are two more equations, M-G EOS and Us-Up curve, as following

$$
\begin{gather*}
P=\rho_{0} c^{2}\left[x+\left(2 s-\frac{\gamma_{0}}{2}\right) x^{2}+s\left(3 s-\gamma_{0}\right) x^{3}\right]+\frac{\gamma_{0} \varepsilon}{v_{0}}  \tag{2.10.4.1}\\
U_{s}=s U_{p}+C \tag{2.10.4.2}
\end{gather*}
$$

where, Pressure $P$, density $\rho_{0}$, internal energy $\varepsilon$, M-G gamma $\gamma_{0}$, stain $x$, shock velocity $U_{s}$ and particle velocity $U_{p}$ are known. There are two equations and two unknown. So Hugoniot slope S and bulk sound speed C can be solved from this equation system.

Table 2.10.4.1 S and C values of Air under different Mach number

| Ma | 1.1 | 1.4 | 1.7 | 2.0 | 2.3 | 2.6 | 2.9 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| S | 3.148 | 0.969 | 0.649 | 0.517 | 0.443 | 0.395 | 0.360 |
| C | 208.013 | 293.862 | 381.402 | 470.106 | 559.651 | 649.824 | 740.481 |

Us-Up curves under different Mach numbers are shown in Figure 2.10.4.1. Intersections between every two curves are the conditions, which are both workable for Rankine-Hugoniot jump condition equation and equation of state of material. Figure 3.4.1 shows that Us-Up relation of air is not linearly, which means that Hugoniot slope S and bulk sound speed C of air vary according to Mach number.


Figure 2.10.4.1: Red curve is the converted Us-Up relation of air based on upstream and downstream Mach numbers. The others are linear Us-Up relation. Intersections are conditions that are both available for Rankine-Hugoniot equations and Us-Up relation.

## Chapter 3

## Gas Simulation Results

### 3.1 Gas Dimensionless Scales Based Simulation

### 3.1.1 B.C. \& Parameters Evaluation

In this section the left hand side boundary conditions (B.C.) are defined as follows:

$$
u=M a, P=\frac{1}{\gamma}, \quad T=1.0, \rho=1.0, e=\frac{P}{\gamma-1}
$$

where, Ma is Mach number, $\gamma$ is specific heat ratio, e is internal energy per unit mass.

The right hand side B.C. can either be determined based on the downstream Mach number supplemented with normal shock equations or which is a subset of the more generalized Rankine-Hugoniot jump equations.

Parameters evaluations for argon and air are presented in Tables 3.1.1.1 and

### 3.1.1.2.

Table 3.1.1.1 Parameters Evaluation, Argon

| Mach\# | $\gamma$ | $\omega$ | Pr | $h_{x}$ | Nodes |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 1.55 | 5/3 | 0.81 | 2/3 | 1/8 | 4800 |
| 3.38 |  |  |  | 1/8 | 4800 |
| 3.38 |  |  |  | 1/16 | 9600 |
| 9.00 |  |  |  | 1/16 | 9600 |
| 9.00 |  |  |  | 1/32 | 19200 |

Table 3.1.1.2 Parameters Evaluation, Air

| Mach\# | $\gamma$ | $\omega$ | $\operatorname{Pr}$ | $h_{x}$ | Nodes |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 1.6 | 1.4 | 0.77 | 0.715 | $1 / 16$ | 9600 |

The dimensionless B.C.s for Argon are presented in Tables 3.1.1.3 through
3.1.1.4.

Table 3.1.1.3 Dimensionless B.C. of Argon, $\mathrm{Ma}=1.55$

|  | $u$ | $\rho$ | $P$ | $T$ | $e$ |
| :---: | :---: | :---: | :---: | :---: | :---: |
| LHS | 1.550 | 1.000 | 0.600 | 1.000 | 0.900 |
| RHS | 0.871 | 1.779 | 1.652 | 1.548 | 2.478 |
| Ratio | 0.562 | 1.779 | 2.753 | 1.548 | 2.753 |

Table 3.1.1.4 Dimensionless B.C. of Argon, $\mathrm{Ma}=3.38$

|  | $u$ | $\rho$ | $P$ | $T$ | $e$ |
| :---: | :---: | :---: | :---: | :---: | :---: |
| LHS | 3.380 | 1.000 | 0.600 | 1.000 | 0.900 |
| RHS | 1.067 | 3.168 | 8.418 | 4.429 | 12.627 |
| Ratio | 0.316 | 3.168 | 14.031 | 4.429 | 14.031 |

Table 3.1.1.5 Dimensionless B.C. of Argon, $\mathrm{Ma}=9.0$

|  | $u$ | $\rho$ | $P$ | $T$ | $e$ |
| :---: | :---: | :---: | :---: | :---: | :---: |
| LHS | 9.000 | 1.000 | 0.600 | 1.000 | 0.900 |
| RHS | 2.333 | 3.857 | 60.600 | 26.185 | 90.900 |
| Ratio | 0.259 | 3.857 | 100.999 | 26.185 | 100.999 |

### 3.1.2 Validation Check

In order to validate the model, Figures 3.1.2.1 presents the shock wave profile of the numerical simulation compared both the theoretical solution [7] and experimental values [10]. The numeric and analytic solutions are nearly identical; the RMS error is $0.2 \mathrm{e}-4$. This is an indication that the numeric scheme is functioning well. However, neither the analytic nor numeric solutions agree well with the experimental data. As can be seen in the figure, the experimentally measured thickness of the shock is wider and the gradients within the shock are smaller as compared to the analytic and numeric solutions. The reasons for this difference in shock thickness can be attributed to the formulation of
the analytic solution. Namely the viscous and diffusive transport properties are assumed constant in the analytic solution. However in reality, temperature variations in the shock front cause significant deviations in the transport properties resulting in a smearing or thickening of the wave. From the experimental result, the thickness of shock front is around 10 times of gas mean free path.


Figure 3.1.2.1: Argon shock profile for Mach number 1.55. Nodes $=4800, \mathrm{hx}=1 / 8$. Analytic and numeric solutions assume constant viscosity.

Figure 3.1.2.2 presents the effect of node numbers on shock wave profile. In order to set boundary in infinity, 300 times mean free path domain is selected experientially firstly. Even though node number doubles, which means the total domain doubles, the gradient and thickness of shock front does not change. Two kinds of marker are identical
in values. Thus 300 times mean free path is enough to be recognized as infinity and larger domain does not affect the shock profile.


Figure 3.1.2.2 Argon shock wave profile for Mach number 1.55, $\mathrm{hx}=1 / 8$. Shock wave profiles of node number 4800 and 9600 are identical.

Figure 3.1.2.3 presents the effect of grid spacing, hx, on shock wave profile. In order to keep the accuracy of the simulation, adequate nodes, i.e. resolution, in shock front are need. The value of the parameter hx, distance between two nodes, corresponds to the number of nodes is related to resolving local gradient. The figure presents the shock profile with two different values of hx, both results in a change in the domain. However, the gradient and thickness of shock front do not change. Thus the domain is
converged for values of hx of $1 / 8$ th or smaller, which is to say the solution is invariant to grid resolution for $\mathrm{hx}<1 / 8$.


Figure 3.1.2.3 Argon shock wave profile for Mach number 1.55, Node $=9600$. Shock wave profiles of $h x=1 / 8$ and $1 / 16$ are identical.

Another important aspect of these solutions is the location of the far stream boundary condition relative to the location of the shock thickness. In the above analysis, the far field boundary conditions, which are applied at infinity, are place 30 times the shock. In the same condition except node number and hx value, this numerical model is not sensitive to these two parameters. Ultimately a value of 300 times of gas mean free was used as the total domain size.

Additionally, parameter ht, time step, can affect the stability of the numerical models. According to the Courant stability criteria [11], the requirement for ht is that the distance local disturbances would travel per time step must be no more than the distance between two nodes. Usually, a Courant-Friedrichs-Lewy (CFL) number ranges from 0.1 to 0.5 [12] is used in order to keep gets accurate and stable simulation.

### 3.1.3 Argon Simulation Analysis - Gas Dimensionless Scale

Figure 3.1.3.1 presents the total entropy change across the shock as a function of iteration number. In addition the theoretical entropy change, equation 2.7.1, across a shock is presented for comparison. The numerically determined entropy converges to the theoretical entropy with iteration, and is nearly identical to the theoretical results from 6.0 in logarithm axis (1 million iterations). Thus one million iterations are enough to get converge the entropy difference. In the following simulations with Mach number of 1.55, iterations are set to 1 million.


Figure 3.1.3.1: Argon, Mach number 1.55, Nodes $=4800, h x=1 / 8$. Entropy changes converge and are identical to theoretical profile within iteration increasing.

Figure 3.1.3.2 presents the change in the sum of entropy generation as a function of iteration number for the four viscosity sub-models. Thus as the simulation proceeds and the solution converges, the total increase in entropy asymptotically approaches a steady value very close to the theoretical value.


Figure 3.1.3.2: Argon, Mach number 1.55, Nodes $=4800$, hx $=1 / 8.4$ types of viscosity models are built. Entropy changes of these sub-models converge in 1M iteration and approach to theoretical value.

Figure 3.1.3.3 presents the shock profiles using several different viscosity models alongside the analytic solution and experimental data for a Mach number 1.55 in argon. The simulations were evolved over 1 million iterations. Shock wave thickness ranges between 10 to 20 times of mean free path of argon. These four sub-models profiles are set in the area between experimental result and analytical result. The power law model is the closest to experimental profile, which consequently has the largest entropy change, as would be expected.


Figure 3.1.3.3: Argon, Mach number 1.55, Nodes $=4800$, hx $=1 / 8$, Domain 300. Shock profiles of 4 different types of viscosity models compare with experimental and analytical solutions in domain 20.

With an increase in Mach number, the shock thickness decreases, thus the number of nodes and the node spacing, hx, are adjusted in order to better resolve the shock profile. Each adjustment related to the number of nodes and node spoacing, hx, is companied with a sensitivity analysis. The relationship between hx, nodes number and total domain size is

$$
\begin{equation*}
\text { Domain }=\frac{\text { Nodes } \times \mathrm{hx}}{2} \tag{3.1.3.1}
\end{equation*}
$$



Figure 3.1.3.4: Entropy Change Error within 30M Iteration. Nodes $=4800, \mathrm{hx}=1 / 8$.

The figure shows that it takes less than 0.1 M iteration for convergence of entropy change. Theoretical entropy change value is $224.6224 \mathrm{~J} / \mathrm{Kg} / \mathrm{K}$, Numerical result converge at $220.7 \mathrm{~J} / \mathrm{Kg} / \mathrm{K}$. There is a $4 \mathrm{~J} / \mathrm{Kg} / \mathrm{K}$ entropy difference compared with theoretical value.


Figure 3.1.3.5: Entropy Change Error within 30M Iteration. Nodes = 9600, hx = 1/16.

The convergence of entropy change takes around 0.1 M iteration. But the difference between theoretical and numerical results is much smaller under the same yaxis gradation, compared with Figure 3.1.3.4.

1 M Iteration. Nodes $=9600, \mathrm{hx}=1 / 16$. Theoretical entropy change value is $224.6224 \mathrm{~J} / \mathrm{Kg} / \mathrm{K}$, Numerical result converge at $223.5 \mathrm{~J} / \mathrm{Kg} / \mathrm{K}$, which is much better than the value from Nodes 4800 , $\mathrm{hx}=1 / 8$. In sum, more nodes and smaller grids distance make larger variation of entropy change and longer iteration for convergence, while more accurate value of entropy changes.

According the sensitive analysis of nodes scales, the number of nodes is set to 9600 and the grid spacing, hx , is set to $1 / 16$ of the mean free path of argon in the following viscosity sub-model simulations.


Figure 3.1.3.6: Entropy Change Trends of Different Viscosity Models, Nodes 9600, hx $=1 / 16$. Entropy changes of these sub-models converge in 1M iteration and approach to theoretical value.


Figure 3.1.3.7: Comparison of Different Viscosity Sub-Models Profiles.

According to the above figure, under Mach number 3.38, shock wave thickness ranges between 10 to 20 times of mean free path of argon. These four sub-models profiles are also set in the area between experimental result and analytical result. Power law model is closest to experimental profile, while with largest entropy change.


Figure 3.1.3.8: Comparison of Analytical and Numerical Results at Constant Viscosity at Mach number 9. This figure shows that when using constant viscosity sub-model, shock wave profile matches analytical simulation, even under large march number.


Figure 3.1.3.9: Entropy Change Error at Constant Viscosity. Node = 9600, hx = 1/16.

The figure also shows that errors of entropy change converge within iteration increasing and entropy changes get stable over 30M iterations. According to figure, theoretical value is around $738.4 \mathrm{~J} / \mathrm{Kg} / \mathrm{K}$, numerical values converge at $739 \mathrm{~J} / \mathrm{Kg} / \mathrm{K}$.


Figure 3.1.3.10: RMS Error of Entropy Changes at Constant Viscosity, Mach number 9.

The figure shows that RMS Errors get stable over 30M iterations and around 0.5. Difference between top and bottom is around $1 \mathrm{~J} / \mathrm{Kg} / \mathrm{K}$. In order to keep the accuracy of simulation, the total number of nodes was increased to 19,200 for the Mach number 9.0 simulation in order to insure the shock slope was well resolved.


Figure 3.1.3.11: Entropy Change Error within 30M Iteration. Nodes $=19200, \mathrm{hx}=1 / 32$.

According to figure, theoretical value is around $738.4 \mathrm{~J} / \mathrm{Kg} / \mathrm{K}$, numerical values converge at $740.8 \mathrm{~J} / \mathrm{Kg} / \mathrm{K}$ for constant viscosity. Compared with Figure 2.7.1.2.12, convergence process under this scale is much faster, which is much shorter than 30M iteration to get stable state, while with larger entropy variation, which is around 200 J/Kg/K.


Figure 3.1.3.12: Entropy Change Trends of Different Viscosity Models, Nodes=19200, $h x=1 / 32$. Entropy changes of these sub-models converge in 1 million iteration and approach to theoretical value.


Figure 3.1.3.13: Comparison of Different Viscosity Sub-Models Profiles, Ma = 9.0, Nodes $=19200, h x=1 / 32$. Domain $=10 \lambda$.

According to the above figure, under Mach number 9.0, shock wave thickness ranges between 10 to 20 times of mean free path of argon. These four sub-models profiles are also set in the area between experimental profile and analytical profile. Power law model is closest to experimental profile, while with largest entropy change.

Table 3.1.1.1 Value of Entropy Change, Argon, Specific Gas Dimensionless Scale

| Mach Number | 1.55 | 3.38 | 9.0 |
| :---: | :---: | :---: | :---: |
| Nodes Number | 4800 | 9200 | 19200 |
| hx | $1 / 8$ | $1 / 16$ | $1 / 32$ |
| Theoretical Solution | 16.51354 | 224.62240 | 738.47375 |
| Constant Viscosity | 16.46207 | 223.53973 | 740.88910 |
| Power Law Model | 16.50063 | 224.52104 | 738.56009 |
| Maxwell Model | 16.46703 | 224.30592 | 740.19109 |
| Chapman-Enskog Model | 16.47625 | 224.48048 | 739.18252 |

### 3.2 General Dimensionless Scales Based Simulation

### 3.2.1 Argon Simulation Analysis - General Dimensionless Scales

In order to keep the same B.C. as chapter 2.7.1 for argon,
Left hand side B.C.

$$
u=M a, P=\frac{1}{\gamma}, \quad T=\frac{1}{\gamma(\gamma-1)}, \rho=1.0, e=T
$$

Right hand side boundary condition is also can be determined Rankine-Hugoniot jump equations.


Figure 3.2.1.1: Entropy Change Trends of Different Viscosity Models, Nodes 4800, $h x=1 / 8, \mathrm{Ma}=1.55$. Entropy changes of these sub-models converge in 1 M iteration and approach to theoretical value $16.4917 \mathrm{~J} / \mathrm{Kg} / \mathrm{K}$. Each sub-model's stable entropy change value is shown in Table 3.2.1.1


Figure 3.2.1.2 Comparison of Different Dimensionless Scales, Ma = 1.55, Domain = $20 \lambda$.


Figure 3.2.1.3: Comparison of Different Dimensionless Scales. $M a=1.55$, Domain $=10 \lambda$.

According to the above figure, under Mach number 1.55, the thicknesses of two shock wave profiles are larger than10 times of mean free path of argon. These four submodels profiles are all set in the area between experimental profile and analytical profile, even thought, profiles under the same B.C. are mismatch. This condition is caused by two types of dimensionless scales. Power law model is closest to experimental profile, while with largest entropy change.


Figure 3.2.1.4: Entropy Change Trends of Different Viscosity Models, Nodes = 9600, hx $=1 / 16, \mathrm{Ma}=3.38$. Entropy changes of these sub-models converge in 1 M iteration and approach to theoretical value $16.4917 \mathrm{~J} / \mathrm{Kg} / \mathrm{K}$. Each sub-model's stable entropy change value is shown in Table 3.2.1.1.


Figure 3.2.1.5: Comparison of Different Dimensionless Scales. $\mathrm{Ma}=3.38$.

Comparing with profiles of Mach number 1.55, all the thicknesses of shock wave profiles are smaller than10 times of mean free path of argon. These four sub-models profiles are all set in the area between experimental profile and analytical profile, Power law model is closest to experimental profile, while with largest entropy change.


Figure 3.2.1.6: Entropy Change Trends of Different Viscosity Models, Nodes = 19200, $h x=1 / 32, \mathrm{Ma}=9.0$. Entropy changes of these sub-models converge in 1 M iteration and approach to theoretical value $16.4917 \mathrm{~J} / \mathrm{Kg} / \mathrm{K}$. Each sub-model's stable entropy change value is shown in Table 3.2.1.1


Normalized Position, x/ $\lambda$
Figure 3.2.1.7: Comparison of Different Dimensionless Scales. $\mathrm{Ma}=9.0$. Comparing with profiles of Mach number 1.55 and 3.38, profiles under the same B.C trend to match each other.

Table 3.2.1.1 Value of Entropy Change, Argon, General Dimensionless Scale

| Mach Number | 1.55 | 3.38 | 9.0 |
| :---: | :---: | :---: | :---: |
| Nodes Number | 4800 | 9200 | 19200 |
| hx | $1 / 8$ | $1 / 16$ | $1 / 32$ |
| Theoretical Solution | 16.49170 | 224.54799 | 738.31049 |
| Constant Viscosity | 16.46207 | 223.53973 | 740.88910 |
| Power Law Model | 16.49263 | 224.51563 | 738.65994 |
| Maxwell Model | 16.46400 | 224.27904 | 740.40087 |
| Chapman-Enskog Model | 16.47370 | 224.47266 | 739.28363 |

### 3.2.2 Air Simulation Analysis - Ideal Gas EOS

Parameters evaluation of air are shown as Table 3.2.2.1

Table 3.2.2.1 Parameters Evaluation, Air, Nodes $=4800$, $h x=1 / 8$.

| Mach\# | $\gamma_{0}$ | $\omega$ | $\operatorname{Pr}$ | $S$ | $C_{0}$ |
| :--- | :--- | :--- | :--- | :--- | :---: |
| 1.4 | 0.4 | 0.77 | 0.715 | 0.968793 | 293.8619 |

Dimensional left hand side B.C. for air simulation is shown in Table 3.2.2.2.

Table 3.2.2.2 Parameters Evaluation, Air, Nodes $=4800, \mathrm{hx}=1 / 8$.

| Mach $\#$ | $\rho_{1}\left(\mathrm{Kg} / \mathrm{m}^{3}\right)$ | $\mathrm{P}_{1}(\mathrm{~Pa})$ | $\mathrm{T}_{1}(\mathrm{~K})$ | $u_{1}(\mathrm{~m} / \mathrm{s})$ |
| :---: | :---: | :---: | :---: | :---: |
| 1.4 | 1.205 | 103.320 | 300.0 | 486.064193 |



Figure 3.2.2.1: Entropy Change Trends of Different Viscosity Models, Air, Ma = 1.4, Nodes 4800, hx = 1/8.

Entropy changes of these sub-models converge in 1M iteration and approach to theoretical value $12.25622 \mathrm{~J} / \mathrm{Kg} / \mathrm{K}$. Each sub-model's stable entropy change value is shown in Table 3.2.2.3.


Figure 3.2.2.2: Entropy Change Trends of Different Viscosity Models, Air, Ma = 1.4, Nodes 4800, hx = 1/8. Entropy changes of these sub-models converge in 1 M iteration and approach to theoretical value $12.25622 \mathrm{~J} / \mathrm{Kg} / \mathrm{K}$. Each sub-model’s stable entropy change value is shown in Table 3.2.2.3.


Figure 3.2.2.3: Comparison of Different Dimensionless Scales. $\mathrm{Ma}=1.4$, Nodes $=4800$, $h x=1 / 8$, Domain $20 \lambda$.


Figure 3.2.2.4: Comparison of Different Dimensionless Scales. $\mathrm{Ma}=1.4$, Nodes $=4800$, $h x=1 / 8$, Domain $10 \lambda$.

Comparing with profiles of argon, these four sub-models profiles have similar trends. Shock wave thicknesses of Power Law profile are 20 times of mean free path of air. Power law model has largest entropy change.

Table 3.2.2.3 Value of Entropy Change, Air, Ideal Gas EOS

| Mach Number | 1.4 |  |
| :---: | :---: | :---: |
| Nodes Number | 1800 |  |
| hx | $1 / 8$ |  |
| Viscosity Sub-Models | Entropy Change (J/Kg/K) |  |
|  | Gas Dimensionless <br> Scales | General Dimensionless <br> Scales |
| Theoretical Solution | 12.25622 | 12.25622 |
| Constant Viscosity | 12.24533 | 12.24533 |
| Power Law Model | 12.30687 | 12.49248 |
| Maxwell Model | 12.23883 | 12.27202 |
| Chapman-Enskog Model | 12.27070 | 12.36467 |

### 3.3 Mie-Grüneisen EOS Model - Argon

In order to research the availability of M-G EOS on gas medium, parameter s and C0 need to be determined as chapter 2 mentioned. Mach number 1.55 is set to keep same B.C. in ideal gas EOS simulation.

Table 3.3.1 Parameters Evaluation, Argon, Nodes $=4800$, $\mathrm{hx}=1 / 8$.

| Mach\# | $s$ | $C_{0}(\mathrm{~m} / \mathrm{s})$ |
| :---: | :---: | :---: |
| 1.55 | 1.00095565 | 207.664409 |



Figure 3.3.1: Entropy Change Trends of Different Viscosity Models, M-G EOS, Argon, $\mathrm{Ma}=1.55$, Nodes $4800, \mathrm{hx}=1 / 8$.

Entropy changes of these sub-models converge in 1M iteration and approach to value $14.33 \mathrm{~J} / \mathrm{Kg} / \mathrm{K}$, which is off the theoretical value of entropy change $16.49 \mathrm{~J} / \mathrm{Kg} / \mathrm{K}$ from ideal gas EOS.


Figure 3.3.2: Comparison of Different Dimensionless Scales, M-G EOS, Argon, $\mathrm{Ma}=1.55$, Nodes $=4800, \mathrm{hx}=1 / 8$, Domain $20 \lambda, \lambda$ is the mean free path of argon.


Figure 3.3.3: Comparison of Different Dimensionless Scales, M-G EOS, Argon, $\mathrm{Ma}=1.55$, Nodes $=4800, \mathrm{hx}=1 / 8$, Domain $10 \lambda$.

The shock wave density profiles are similar to those from ideal gas EOS, Power Law model is the closet one to experimental result, then Chapman-Enskog model.

Maxwell model almost overlaps with constant viscosity model. The difference is that all the viscosity sub-models in M-G EOS are more approaching experimental result. Especially; Power Law model result is closer to experimental result. Shock wave thicknesses range from 10 to 15 times of mean free path.


Figure 3.3.4: Heat Flux and Stress relationship, Constant Viscosity, Argon, Ma = 1.55, Nodes $=4800, \mathrm{hx}=1 / 8$. M-G EOS result has smaller absolute value in both heat flux and stress.


Figure 3.3.5: Heat Flux and Stress relationship, Power Law model, Argon, $\mathrm{Ma}=1.55$,
Nodes $=4800, \mathrm{hx}=1 / 8$.


Figure 3.3.6: Heat Flux and Stress relationship, Maxwell model, Argon, $\mathrm{Ma}=1.55$, Nodes $=4800, \mathrm{hx}=1 / 8$.


Figure 3.3.7: Heat Flux and Stress relationship, Chapman-Enskog model, Argon, $\mathrm{Ma}=1.55$, Nodes $=4800, \mathrm{hx}=1 / 8$.

Table 3.2.2.3 Value of Entropy Change, Argon, General Dimensionless Scales

| Mach Number | 1.55 |  |
| :---: | :---: | :---: |
| Nodes Number | 4800 |  |
| hx | $1 / 8$ |  |
| Viscosity | Entropy Change (J/Kg/K) |  |
| Sub-Models | Ideal Gas EOS | M-G EOS |
| Theoretical Solution | 16.49170 | 16.49170 |
| Constant Viscosity | 16.46207 | 14.33946 |
| Power Law Model | 16.49263 | 14.43678 |
| Maxwell Model | 16.46400 | 14.34159 |
| Chapman-Enskog Model | 16.47370 | 14.36217 |

### 3.4 Summary

In chapter 3, two types of dimensionless scales are used and compared in argon and air simulation. Four types of viscosity modes are used to simulated shock profiles in argon and air for different Mach numbers. Entropy change errors of these sub-models are smaller than ten thousandth. The Power Law model profile is closest to the experimental result, followed with Chapman-Enskog and Maxwell model. The power law is derived from a fit to experimental data whereas Maxwell model and Chapman-Enskog model are hard sphere and soft sphere theoretical models respectively. Shock wave thickness becomes thinner when Mach number increases and as a result more difficult to resolve.

M-G EOS and Ideal Gas EOS are derived based on different assumption and physical principles from statistic mechanics. M-G EOS mainly focus on the internal energy contributed from vibration energy of oscillators, while for gas, most of the internal energy are contributed by translational kinetic energy not rotation or vibration energy. That's one main explanation for the differences in entropy change across the shock for the different equations of state.

## Chapter 4

## Mie-Grüneisen EOS Model - Water

### 4.1 Experimental Geometry

Measurement of shock wave pressure is conducted by University of Cambridge
[13]. Figure 4.1.1 is the geometry of experiment.


Figure 4.1.1: Experiment schematic of shock wave pressure in water.

Copper flyer hitting the O-ring causes shock wave transmitting in water, which is detected by rear gauge.The initial temperature for stationary water is $18 \pm 2 \mathrm{C}$. The copper flyer is traveling at $295 \mathrm{~m} / \mathrm{s}$ towards O-ring. The thickness of gauge is neglected.

### 4.2 Determination of Shock Wave Velocity

An impedance matching technique in pressure-particle velocity, P-Up, space is used to determine shock velocity in water. [8]

$$
\begin{gather*}
P_{\text {water }}=\rho_{\text {water }} C_{\text {water }} U_{p}+\rho_{\text {water }} S_{\text {water }} U_{p}^{2}  \tag{4.2.1}\\
P_{\text {copper }}=\rho_{\text {copper }} C_{\text {copper }}\left(U_{\text {flyer }}-U_{p}\right)+\rho_{\text {copper }} S_{\text {copper }}\left(U_{\text {flyer }}-U_{p}\right)^{2} \tag{4.2.2}
\end{gather*}
$$

Solving equation (4.2.1) and equation (4.2.2), Up and Us can be derived. Table 4.2.1 and Figure4.2.1 are results of impedance match.

Table 4.2.1 Parameters and results of impedance match

| Material | Flyer velocity $(\mathrm{m} / \mathrm{s})$ | Temperature $(\mathrm{k})$ | S | $\mathrm{C}(\mathrm{m} / \mathrm{s})$ | $\rho\left(\mathrm{kg} / \mathrm{m}^{3}\right)$ | $\mathrm{Up}(\mathrm{m} / \mathrm{s})$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Copper | 295 | 293.15 | 1.49 | 3940 | 8930 | 277.8668 |
|  | Water |  |  | 1.92 | 1650 | 1000 |
|  |  |  |  |  |  |  |



Figure 4.2.1: Impedance match of Us-Up lines.

The intersection is the final condition after impact. Up is the particle velocity of water, which can be used to calculate shock wave velocity in water. According to chapter 2, pre-shock and post-shock flow velocities, U1 and U2, can be converted from known Us and Up values.

### 4.3 Mie-Grüneisen Parameter

As chapter 2 mentioned, boundary conditions of shock wave in water also can be determined by Rankine-Hugoniot jump condition equations. The Mie-Grüneisen EOS is a function incorporating pressure, internal energy, Hugoniot slope, bulk sound speed, strains and Mie-Grüneisen gamma. As all the parameters except M-G gamma are determined though the above impedance matching process, M-G gamma can be derived
based on the assumption that shock wave boundary conditions are both available in Rankine-Hugoniot jump condition equations and M-G EOS as shown in Figure 4.3.1.


Figure 4.3.1: Dimensionless impedance match to derive $\mathrm{M}-\mathrm{G}$ gamma. X axis is the specific volume; Y axis is the pressure. Blue is M-G EOS; Green is Rayleigh line;

Red is post-shock pressure and yellow is pre-shock pressure.

### 4.4 Relation of Bulk Viscosity and Dilatational Viscosity

During the research of shock wave in water, in order to get better understanding and make use of literature data accurately, one of the difficulties is that notations in literatures can be different. For liquid, stress is not only related to first viscosity but also related to second viscosity. First viscosity is the dynamic viscosity. Second viscosity has at least two kinds of notations, bulk viscosity or dilatational viscosity. Bulk viscosity is used in Compressible-Fluid Dynamics, Philip.A.T, expressed in viscous stress equation

$$
\begin{equation*}
\sum_{i k}=2 \mu\left(D_{i k}-\frac{1}{3} \delta_{i k} D_{m m}\right)+\mu_{\nu} \delta_{i k} D_{m m} \tag{4.4.1}
\end{equation*}
$$

Where, $\mu$ is the first viscosity,

$$
\begin{align*}
D_{i k} & =\frac{1}{2}\left(\frac{\partial v_{j}}{\partial x_{i}}+\frac{\partial v_{i}}{\partial x_{j}}\right)  \tag{4.4.2}\\
D_{m m} & =\left(\frac{\partial v_{x}}{\partial x}+\frac{\partial v_{y}}{\partial y}+\frac{\partial v_{z}}{\partial z}\right), \tag{4.4.3}
\end{align*}
$$

Replace $D_{i k}$ and $D_{m m}$ in equation (4.4.1) and rearrange it, get

$$
\begin{equation*}
\sum_{i k}=\mu\left(\frac{\partial v_{j}}{\partial x_{i}}+\frac{\partial v_{i}}{\partial x_{j}}\right)-\left(\frac{2}{3} \mu-\mu_{v}\right)\left(\frac{\partial v_{x}}{\partial x}+\frac{\partial v_{y}}{\partial y}+\frac{\partial v_{z}}{\partial z}\right) \delta_{i k} \tag{4.4.4}
\end{equation*}
$$

Equation (4.4.4) is just opposite to the equation in Transport Phonomena, 2nd
Edition, R.B.Bird.

$$
\begin{equation*}
\tau_{i k}=-\mu\left(\frac{\partial v_{j}}{\partial x_{i}}+\frac{\partial v_{i}}{\partial x_{j}}\right)+\left(\frac{2}{3} \mu-\mu_{v}\right)\left(\frac{\partial v_{x}}{\partial x}+\frac{\partial v_{y}}{\partial y}+\frac{\partial v_{z}}{\partial z}\right) \delta_{i k} \tag{4.4.5}
\end{equation*}
$$

So, for one dimensional shock wave, simplified stress is

$$
\begin{equation*}
\Pi_{x x}=\sum_{x x}=-\tau_{x x} \tag{4.4.6}
\end{equation*}
$$

As a result, bulk viscosity is the same as dilatational viscosity in same coordinate.

$$
\begin{equation*}
\kappa=\mu_{v} \tag{4.4.7}
\end{equation*}
$$

Second viscosity reference value is from Compressible-Fluid Dynamics,

## Philip.A.T, Table 1.1.

### 4.5 Numerical Simulation

Left hand side dimensional B.C.
$u=M a, P=1 \mathrm{~atm}, T=300 \mathrm{k}, \rho=1000 \mathrm{~kg} / \mathrm{m}^{3}, e=\frac{P}{\gamma_{0}}$
where, $\gamma_{0}$ is M-G gamma, e is internal energy per unit mass.

Right hand side B.C. is determined by impact impedance match and RankineHugoniot jump equations.

Parameters evaluations for water are presented in Table 4.5.1 and Dimensionless B.C.s of water are shown in Table 4.5.2.

Table 4.5.1 Parameters Evaluation, Water

| Mach\# | Up | S | C 0 | $\gamma_{0}$ | $u v$ | $h_{x}$ | Nodes |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 1.323 | 277.867 | 1.920 | 1650 | 4.984 | 3.100 | $1 / 8$ | 4800 |

Table 4.5.2 Dimensionless B.C. of Water, $\mathrm{Ma}=1.32$

|  | $u$ | $\rho$ | $P$ | $T$ | ie |
| :--- | :--- | :--- | :--- | :--- | :--- |
| LHS | 1.323 | 1.000 | $3.722 \mathrm{e}-5$ | 0.455 | $7.467 \mathrm{e}-6$ |
| RHS | 1.155 | 1.146 | 0.223 | 0.469 | 0.780 |
| Ratio | 0.872 | 1.146 | 5988.894 | 1.031 | 104459.622 |

### 4.6 Sensitivity Analysis

Datas from NIST [15] are incorporated in numerical code to conduct sensitivity analysis of shock wave thickness.

### 4.6.1 Specific Heat at Constant Volume (Cv)



Figure 4.6.1: Specific Heat Effect on Shock Wave Thickness. This figure shows that varying specific heat contributes the same shockwave profile as constant specific heat. Conclusion is that shock wave thickness is not obviously sensitive to the specific heat.

### 4.6.2 Heat Conductivity (k)



Figure 4.6.2: Heat Conductivity Effect on Shock Wave Thickness.

This figure shows that varying Heat Conductivity contributes the same shockwave profile as constant heat conductivity. Conclusion is that shock wave thickness is not obviously sensitive to the heat conductivity.

### 4.6.3 Viscosity ( $\mu$ )



Figure 4.6.3: Viscosity Effect on Shock Wave Thickness.

This figure shows that varying viscosity contribute slightly difference to the profile compared with constant viscosity. As known, viscosity of water decreases when temperature rises. The slope of shock wave profile gets greater matching the conclusion from gas. So shock wave thickness is weakly sensitive to the viscosity.

### 4.6.3 Length Scale



Figure 4.6.4: Effect of Length Scale on Shock Wave Thickness. This figure shows that varying lambda contribute the same shockwave profile as former molecular diameter.

Conclusion is that shock wave thickness is not sensitive to the length scale.

## Chapter 5

## Conclusion

In order to develop a better understanding of the irreversibilities associated with the shock compaction of fluids, 3 materials (argon, air and water), 2 equations of state (EOS) (Ideal Gas EOS and Mie-Grüneisen EOS incorporated with Material EOS) and 4 viscosity sub models are studied in one-dimension via a numerical solution. The numerical solution is validated with the analytical solution for perfect gas behavior and compared to experimental data where available.

A non-dimensional numeric scheme based upon an explicit Eulerian finite volume method was developed. The spatial resolution converges at less than $1 / 8^{\text {th }}$ of the mean free path, ensuring the stability of the numerical algorithm without resorting to implementing artificial dissipation. Space derivatives are approximated by second order central differences and time derivatives are approximated by first order forward differences.

Initial simulations focused on argon, i.e. a monatomic perfect gas. Simulation boundaries are set more than ten shock wave thickness away from the shock. Simulations indicate that shock wave thickness becomes thinner as Mach number increases up to a Mach number of 9 . Simulated density profiles slightly differ from experimental results. From the shock profiles, the entropy change can be calculated. Entropy change provides a single metric as to the quality of the simulation, when compared to the theoretical entropy change. The theoretical entropy change for a perfect gas is around $0.3 \%$ different to the
simulated entropy change of the viscous models considered in this work, the Maxwell model for viscosity gives results which are closed to the analytic solution, whereas the Power Law viscous model results in profiles that most resemble the experimental data. The Power Law viscous model results in the largest value of entropy change at low Mach numbers (Mach number 1.55 and 3.38), but the smallest value of entropy change at large Mach number (Mach number 9), compared with other viscous models.

Next, the shock wave profile in a non-monatomic gas, i.e. air, is simulated for Mach number 1.4. The results indicate similar phenomena as argon at low Mach number (Mach number 1.55).

While validating the Mie-Grüneisen (M-G) EOS for shock waves in fluids, several challenges are resolved. The shock Hugoniot equation, used as the reference curve for the M-G EOS for gas was derived. The relationship between equivalent M-G constant and the ratio of specific heat was derived. When modeling gaseous argon passing through a shock at Mach number 1.55, the M-G EOS predicts lower entropy change, $14.437 \mathrm{~J} / \mathrm{Kg} / \mathrm{K}$, as compared to the ideal gas EOS, which predicts in 16.493 $\mathrm{J} / \mathrm{Kg} / \mathrm{K}$. The main reason causing this difference is discussed in chapter 3 . Finally, it is observed that heat flux dominates the entropy change for M-G EOS.

Finally the M-G EOS for water was numerically investigated and the results were compared to experimental data. The M-G constant is derived by impedance matching the M-G EOS and Rayleigh line. The bulk viscosity is also incorporated into the stress term. From a parametric study of transport properties, it was found that the shock wave thickness is weakly sensitive to the specific heat, heat conductivity, viscosity and grid
dimension, whereas changes in the viscosity have the largest effect on the shock profile thickness. However, the shock wave thickness, even at varying viscosities still too thin compared to experimental data.

This research mainly focuses on deriving a suitable set of equations for doing direct numeric simulations of shock profiles in gasses and liquid and then numerically solving these equations using a finite volume technique. Simulations of shock wave in liquids and gases serve as a bridge to better understand the applicability of the M-G EOS for resolving the shock profiles in solids. This is especially true when considering the viscous dissipation mechanisms in solids across the shock. Further considerations from statistical mechanics might provide more insight in the future; by supporting assumptions with more precise governing equations; the simulated shock wave profiles may be better resolved.

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## APPENDIX - FORTRAN CODE

```
    parameter(jj=4800)
    parameter(limit = 99999999)
    real*8 T(0:jj),rho(0:jj),p(0:jj),u(0:jj),E(0:jj),eta(0:jj)
    real*8 rhohat(0:jj),uhat(0:jj), Ehat(0:jj), phat(0:jj),jhat(0:jj)
    real*8 j(0:jj),PI(0:jj),q(0:jj),H(0:jj)
    real*8 Pr, gama,mu, R, Tinf, rhoinf, cinf, lambda, etainf
    real*8 hx, ht, Ma, w
    real*8 c1, x0, M1, v1, alpha, beta
    real*8 xa, xb, xx, dx, fa, fb
    real*8 psi(0:jj),etad(0:jj)
    real*8 m0, m, k0, k, sigma0, sigma
    real*8 ratioe, Tinter, x, omegau(0:jj)
    real*8 Cv,kappa, deltax, dsa, ds, dsu(0:jj), dsT(0:jj), dsus,
dsTs
    real*8 gama0, gama00,Pref,eref,rhoref, Pinter, entropy(0:limit)
    real*8 ie(0:jj),ke(0:jj)
    real*8 Pless, rholess, Tless, eless, kaless,kappa0
    real*8 Mmass, uv, e00, e01, e02, e03, e04, s, C, e0, einter,c0
    real*8 Temperature, Cv0,CvD, gam0, Us, Up, P0
    real*8 sa, sb, fs, u0, u1
    integer i,eos, counter, bug
    character*14 filen
c character*14 entropy
    character*1 ans
c M-G gamma: gama0 reference pressure: Pref
c reference internal energy: eref
    entropy = 'en00000000.dat'
    filen = 'ns00000000.dat'
c open(unit=23,file='zeta.dat',form='formatted',status='unknown')
c.........................Choose EOS
c eos=0,1,2,4, Gas. eos = 3 liquid
c eos = 0,ideal gas EOS with Gas Specific Dimensionless Scales
c eos = 1,M-G for gas, General Dimensionless Scales
c eos = 2,M-G general dimensionless, need check
c eos = 3,water M-G, general dimensionless
c eos = 4,ideal gas eos, General Dimensionless scales
    eos = 1
c..........................Parameters..............................
c-------------------------------Gas--------------------------------
    if(eos .ne. 3) then
c s= 1.059d0 ! Hugoniot slope, Air, JAP experiment
c C0 = 243.d0 ! Bulk sound speed, Air, JAP experiment
c s = 0.4086132999 ! Ma=2.5 Air solved value from maple, 3rd
order eos
```

```
c C0 = 619.7064063 ! Ma=2.5 Air solved value from maple, 3rd
order eos
c s = 0.3878659442 ! Ma=2.5 Air solved value from maple, 4th
order eos
c C0 = 632.3120897 ! Ma=2.5 Air solved value from maple, 4th
order eos
c s = 0.9687928698 ! Ma=1.4 Air solved value from maple, 3rd
order eos
c C0 = 293.8619384 ! Ma=1.4 Air solved value from maple, 3rd
order eos
    s = 1.0009556d0 ! Ma = 1.55, Argon
    C0 = 207.66440d0 ! Ma = 1.55, Argon
    w = 0.81d0 ! Argon
c w = 0.77d0 ! Air
    Ma = 1.55d0 ! Argon
c Ma =1.4d0 ! Air
c Pr = 0.715d0 ! Air
    Pr = 2.d0/3.d0 ! Argon
        gama = 1.4d0 !Air
    gama = 5.d0/3.d0 ! Argon
c mu = 1.80d-5 ! kg/m/s Air JB
c mu = 1.983d-5 ! Kg/m/s Air viscosity online data
c mu = 2.27d-5 ! kg/m/s Argon viscosity online data
    mu = 1.3275d-5 ! kg/m/s Argon NIST data
c kappa = 0.0252793d0 ! W/m/k Air Forced kappa
c kappa = 0.0240d0 ! W/m/k Air heat conductivity,
c Another way is force fromideal gas kappa = gama*R*eta/(gama-1)/Pr
    kappa = 0.0163d0 ! W/m.k Argon heat conductivity
    R = 208.1d0 ! J/kg/K Argon
C R = 287.0d0 ! J/Kg/K Air
C CV = 718.d0 ! J/Kg/K Air from online data
        Cv = 717.5d0 ! J/kg/k Air from ideal gas Eos
        Cv = R/(gama-1.d0) ! J/kg/k Air ideal gas, analytical
    c CV = 312.2d0 !J/kg/K Argon
C Tinf = 300.d0 ! kelvin, k
c Pref = 103.320d3 ! Pa
    Tinf = 164.d0 ! Helium from Muntz, same for Argon and Air
    Tref = Tinf
c rhoinf = 1.205d0 ! Kg/m^3 Air
c rhoinf = 1.2d0 ! kg/m^3 Air JB
    rhoinf = 1.62d0 !kg/m^3 Argon - see BSL notes
    rhoref = rhoinf
    Pref = rhoinf*R*Tinf ! Analytical Pressure from Gas EOS
    cinf = dsqrt(gama*R*Tinf) ! [m/s] upstream sound speed
c C0 = cinf ! for gas with analytical sound speed
    etainf = gama**(w-0.5d0)*5.d0*sqrt(2.d0*acos(-1.d0))/16.d0
    & *(1.d0/gama)**W !dimensionless far field viscosity
    lambda = 3.d0*mu*sqrt(acos(-1.d0)/8.d0/R/Tinf)/rhoinf ! hard
sphere mean free path
    eta(0) = mu/(rhoinf*cinf*lambda) ! dimensionless pre-shock
viscosity
c eta(0) = etainf*(T(0))**w
c m0 = 28.964d-3/(6.022d23) ! kg molecule mass of Air
    m0 = 39.948d-3/(6.022d23) ! kg molecule mass of Argon
```

```
    k0 = 1.38066d-23 ! J/kg Boltzmann's constant
c sigma0 = 3.617d-10
    sigma0 = 3.432d-10
    ! m Diameter Air
        ! m Diameter Argon
    m = m0/(rhoinf*lambda**3)
    ! dimensionless m
    k = k0/(rhoinf*R*gama*lambda**3) ! dimensionless k
    sigma = sigma0/lambda ! dimensionless sigma
    ratioe = 122.4d0 ! K Kelvin, Argon
c ratioe = 97.d0 ! K Kelvin, Air
c Tinter = cinf**2/(gama*R*ratioe) ! Gas Dimensionless Scales
    Tinter = cinf**2/(Cv*ratioe) ! General Dimensionless Scales
    gama0 = gama - 1.d0
c kaless = gama*R*rhoinf*cinf*lambda ! Gas Dimensionless Scales
    kaless = Cv*rhoinf*cinf*lambda ! General Dimensionless
Scales
    kappa0 = kappa/kaless ! dimensionless heat conductivity, General
Dimesionless scale
c..................shock velocity from Ma number
    u0 = Ma*cinf
    u1 = Ma*(2.d0+(gama-1.d0)*Ma**2)/((gama+1.d0)*Ma**2)*cinf
    Us = u0
    Up = Us - u1
    print *,'Mach Number Ma', Ma
    print *,'Shock velocity Us', Us
    print *,'Partical velocity Up', Up
c pause
c print *, kappa0,eta(0)/((gama-1.d0)*Pr)
c pause
c print *,'bulk and local sound velocity',cinf,c0
c cinf = C0
c print *, cinf
c-----------------------------Liuquid-------------------------------
    elseif (eos .eq. 3) then
c-----------------------EOS parameters------------------------
    Up = 277.8668114d0 ! m/s ! cambridge expriment, impedance match
    s = 1.92d0 ! Hugoniot slope, Meyers book P133
    C0 = 1650.d0 ! m/s, Bulk sound speed, Meyers book P133
    Us = Up*s+C0
    gama0 = 4.984362390d0 ! Gruneisen gama, impedance match from
maple
c----------------------------properties---------------------------
c mu = 0.798d-3 !kg/m/s viscosity, water online data
    mu = 0.85258d-3 ! kg/m/s viscosity, water,NIST(300k,1g/cm^3)
c kappa = 0.58d0 !w/m/k heat conductivity,water
    kappa = 0.61384d0 !w/m/k heat conductivity,water,NIST(300k,
1g/cm^3)
    Cp = 4159.3d0 !J/kg/K specific heat,water,NIST(300k,1g/cm^3)
    Cv = 4105.1d0 ! J/kg/K specific heat,water,NIST(300k,1g/cm^3)
    Mmass = 18.01528d0 !g-mol molar mass, water
    R = 8.31451d3/Mmass ! J/kg/K water
```

```
c-----------------------dimensionless scale--------------------
    Tref = 300.d0 !k,upstream Temperature
    Tinf = Tref
    rhoinf = 1000.d0 ! kg/m^3,water
    cinf = C0 !m/s, upstream sound speed
    Pref = 1.01325d5 !pa, upstream pressure
    lambda = ((Mmass*0.001d0)/(rhoinf*6.02d23))**(1.d0/3.d0) !space
scale, average distance of water molecular
    print *, 'lambda',lambda
    pause
    eta(0) = mu/(rhoinf*cinf*lambda) ! dimensionless viscosity
    kappa0 = kappa/(Cv*rhoinf*cinf*lambda) !dimensionless heat
conductivity
        uv = 3.1d0 !dimensionless bulk viscosity
        endif
c................initial contant viscosity coefficient.........
    do i=0,jj
    eta(i) = eta(0) ! 10**5
    enddo
c.........................dimensionless scales
c cinf = c0
    Tless = cinf**2/Cv
    Pless = rhoinf*cinf**2
    rholess = rhoinf
    eless = Pless
c print *, Tless, Pless, rholess, eless,Cv
c pause
c-------------------initial spece and time step-----------------
    ht=1.0d-8
    hx=0.25d0/2.d0
    deltax = hx*1.d0
c------------------set boundary conditions---------------------
    if(eos .eq. 0) then
    p(0) = 1.d0/gama
c pressure = p(0)*gama
    rho(0) = 1.d0
    u(0) = Ma
    T(0) = gama*p(0)/rho(0)
    j(0) = rho(0)*u(0)
    ie(0) = p(0)/(gama - 1.d0)
    ke(0) = rho(0)*u(0)**2/2.d0
    e(0) = ie(0) + ke(0)
    dsus = 0.d0 ! sum of entropy form stress
    dsu(0) = 0.d0 ! stress entropy term
    dsTs = 0.d0 ! sum of entropy from T
    dsT(0) = 0.d0 ! T entropy term
    omegau(0) = 1.16145d0/((Tinter*T(0))**0.14874d0) ! Chapman-
Enskog
```

```
    & + 0.52487d0/(exp(0.77320d0*Tinter*T(0)))
    & + 2.16178d0/(exp(2.43787d0*Tinter*T(0)))
    eta(0) = 5.d0*dsqrt(m*k*T(0)/acos(-1.d0))
& /(16.d0*omegau(0)*sigma**2)
c eta(0) = 2.d0*dsqrt(m*k*T(0)/acos(-1.d0))
c & /(3.d0*acos(-1.d0)*sigma**2) ! Maxwell
    x = T(0)*Tinf/vari0
    & + 5.485d0*x**2
    & -5.9588d0*x + 4.1996d0
        etad(0) = 5.d0*dsqrt(acos(-1.0)*m*k*T(0))/
    & ((16.d0*acos(-1.0)*sigma**2*omegau)*(rhoinf*cinf*lambda))
    eta(0) = etad(0)/(rhoinf*cinf*lambda)
        eta(0) = etainf*(T(0))**w ! Power Law
    p(jj) = 4.5000*p(0)
    T(jj) = 1.6875*T(0)
    rho(jj) = 2.667*rho(0)
    u(jj) = 0.5774
    j(jj) = rho(jj)*u(jj)
    e(jj) = rho(jj)*u(jj)*u(jj)/2 + p(jj)/(gama-1)
    rho(jj) = rho(0)*(gama+1.d0)*Ma**2/((gama-1.d0)*Ma**2+2.d0)
    u(jj) = rho(0)*u(0)/rho(jj)
    p(jj) = rho(0)*u(0)**2 + p(0) - rho(jj)*u(jj)**2
    ie(jj) = (ie(0)+u(0)**2/2.d0+p(0)/rho(0)-u(jj)**2/2.d0
& -p(jj)/rho(jj))*rho(jj)
    print *, 'rankine', u(jj),p(jj),ie(jj)
    u(jj) = u(0)*(2.d0+(gama-1.d0)*Ma**2)/((gama+1.d0)*Ma**2)
    p(jj) = p(0)*(2.d0*gama*Ma**2-gama+1.d0)/(gama+1.d0)
    e(jj) = rho(jj)*u(jj)*u(jj)/2.d0 + p(jj)/(gama-1.d0)
    ie(jj) = p(jj)/(gama - 1.d0)
    print *, 'eos', u(jj),p(jj),ie(jj)
    pause
    T(jj) = gama*p(jj)/rho(jj)
    dsu(jj) = 0.d0 ! stress entropy term
    dsT(jj) = 0.d0 ! T entropy term
c
c eta(jj) = 2.d0*dsqrt(m*k*T(jj)/acos(-1.d0))
c & /(3.d0*acos(-1.d0)*sigma**2) ! Maxwell
    omegau(jj) = 1.16145d0/((Tinter*T(jj))**0.14874d0) ! Chapman-
Enskog
    & + 0.52487d0/(exp(0.77320d0*Tinter*T(jj)))
    & + 2.16178d0/(exp(2.43787d0*Tinter*T(jj)))
    eta(jj) = 5.d0*dsqrt(m*k*T(jj)/acos(-1.d0))
& /(16.d0*omegau(jj)*sigma**2)
c x = T(jj)*Tinf/vari0
```

```
    omegau \(=-0.0799 \mathrm{~d} 0 * \mathrm{x}^{* *} 5+0.743 \mathrm{~d} 0^{*} \mathrm{x}^{* *} 4-2.7973 \mathrm{~d} 0^{*} \mathrm{x}^{* *} 3\)
    \& + 5.485d0* \(x^{* * 2}\)
    \& \(-5.9588 d 0 * x+4.1996 d 0\)
        etad(jj) \(=5 . d 0 * d s q r t\left(\operatorname{acos}(-1.0) * m^{*}{ }^{*} T(j j)\right) /\)
    \& ((16.d0*acos(-1.0)*sigma**2*omegau)*(rhoinf*cinf*lambda))
    eta(jj) \(=\) etad(jj)/(rhoinf*cinf*lambda)
    Cv0 = ie(jj)/rho(jj)/T(jj)
    CvD = Cv0*gama*R
    print *,Pr, gama, mu, R, Tinf, rhoinf, cinf,lambda, eta(0)
    print *, kappa0,eta(0)/((gama-1.d0)*Pr)
    pause
    elseif(eos .eq. 4) then
    pressure \(=p(0)\) *gama
    rho(0) \(=1 . d 0\)
    \(\mathrm{u}(0)=\mathrm{Ma}\)
    \(\mathrm{T}(0)=1 . \mathrm{d} 0 /(\) gama* (gama-1.d0) \()\)
    \(p(0)=r h o(0) *(\) gama-1.d0)*T(0)
    \(j(0)=r h o(0) * u(0)\)
    ie(0) \(=p(0) /(g a m a-1 . d 0)\)
    \(\mathrm{ke}(0)=\mathrm{rho}(0){ }^{*} \mathrm{u}(0)^{* *} 2 / 2 . \mathrm{d} 0\)
    \(e(0)=i e(0)+k e(0)\)
    dsus \(=0 . d 0 \quad\) ! sum of entropy form stress
    dsu(0) = 0.d0 ! stress entropy term
    dsTs = 0.d0 ! sum of entropy from T
    dsT(0) = 0.d0 ! T entropy term
c omegau(0) = 1.16145d0/((Tinter*T(0))**0.14874d0) ! Chapman-
```



```
\(c \quad \& \quad+2.16178 \mathrm{~d} 0 /\left(\exp \left(2.43787 \mathrm{~d} 0 *\right.\right.\) Tinter*T(0) \(\left.^{\mathrm{T}} \mathrm{C}\right)\)
c eta(0) = 5.d0*dsqrt(m*k*T(0)/acos(-1.d0))
    \& \(\quad\) (16.d0*omegau(0)*sigma**2)
    eta(0) = 2.d0*dsqrt(m*k*T(0)/acos(-1.d0))
    \& /(3.d0*acos(-1.d0)*sigma**2) ! Maxwell
    x = T(0)*Tinf/vari0
    omegau \(=-0.0799 \mathrm{~d} 0 * \mathrm{x}^{* *} 5+0.743 \mathrm{~d} 0 * \mathrm{x}^{* *} 4\) - 2.7973d0*x**3
    \& \(\quad+5.485 d 0 * x^{* *} 2\)
    \& \(\quad-5.9588 d 0 * x+4.1996 d 0\)
    etad \((0)=5 . d 0 * d s q r t\left(\operatorname{acos}(-1.0) * m^{*} k^{*} T(0)\right) /\)
    \& ((16.d0*acos(-1.0)*sigma**2*omegau)*(rhoinf*cinf*lambda))
    eta(0) \(=\) etad(0)/(rhoinf*cinf*lambda)
    eta \((0)=\) etainf* \((T(0))^{* *}\) w Power Law
    \(p(j j)=4.5000^{*} p(0)\)
    \(T(j j)=1.6875 * T(0)\)
    rho(jj) \(=2.667 * r h o(0)\)
    \(u(j j)=0.5774\)
    \(j(j j)=r h o(j j) * u(j j)\)
    \(\mathrm{e}(\mathrm{jj})=\operatorname{rho}(\mathrm{j} j)^{*} u(\mathrm{jj}) * u(j j) / 2+\mathrm{p}(j j) /(\) gama-1)
```

Enskog
C \&

```
        rho(jj) = rho(0)*(gama+1.d0)*Ma**2/((gama-1.d0)*Ma**2+2.d0)
        u(jj) = rho(0)*u(0)/rho(jj)
        p(jj) = rho(0)*u(0)**2 + p(0) - rho(jj)*u(jj)**2
        ie(jj) = (ie(0)+u(0)**2/2.d0+p(0)/rho(0)-u(jj)**2/2.d0
    &
        -p(jj)/rho(jj))*rho(jj)
    print *, 'rankine', u(jj),p(jj),ie(jj)
    u(jj) = u(0)*(2.d0+(gama-1.d0)*Ma**2)/((gama+1.d0)*Ma**2)
    p(jj) = p(0)*(2.d0*gama*Ma**2-gama+1.d0)/(gama+1.d0)
    e(jj) = rho(jj)*u(jj)*u(jj)/2.d0 + p(jj)/(gama-1.d0)
    ie(jj) = p(jj)/(gama - 1.d0)
    print *, 'eos', u(jj),p(jj),ie(jj)
c pause
    T(jj) = p(jj)/(rho(jj)*(gama-1.d0))
    dsu(jj) = 0.d0 ! stress entropy term
    dsT(jj) = 0.d0 ! T entropy term
c pause
c eta(jj) = etainf*(T(jj))**w ! power law
c e eta(jj) = 2.d0*dsqrt(m*k*T(jj)/acos(-1.d0)) /(3.d0*acos(-1.d0)*Sigma**2) M Maxwell
c omegau(jj) = 1.16145d0/((Tinter*T(jj))**0.14874d0) ! Chapman-
Enskog
c & + 0.52487d0/(exp(0.77320d0*Tinter*T(jj)))
c & + 2.16178d0/(exp(2.43787d0*Tinter*T(jj)))
c eta(jj) = 5.d0*dsqrt(m*k*T(jj)/acos(-1.d0))
c & /(16.d0*omegau(jj)*sigma**2)
c x = T(jj)*Tinf/vari0
c omegau = -0.0799d0*x**5 + 0.743d0*x**4 - 2.7973d0*x**3
c & + 5.485d0* x**2
c & -5.9588d0*x + 4.1996d0
    etad(jj) = 5.d0*dsqrt(acos(-1.0)*m*k*T(jj))/
    & ((16.d0*acos(-1.0)*sigma**2*omegau)*(rhoinf*cinf*lambda))
        eta(jj) = etad(jj)/(rhoinf*cinf*lambda)
        Cv0 = ie(jj)/rho(jj)/T(jj)
        CvD = Cv0*gama*R
        print *,Pr, gama, mu, R, Tinf, rhoinf, cinf,lambda,eta(0)
        print *, kappa0,eta(0)/((gama-1.d0)*Pr)
        pause
    elseif(eos .eq. 1) then ! M-G,AIR
c...............coefficients of epsilon in M-G................
    e00 = Cv*Tref/(cinf**2) ! positive or negative? question
    e01 = gama0*e00
    e02 = (c0**2/(cinf**2)+gama0**2*e00)/2.d0
    e03 = (4.d0*s*C0**2/(cinf**2)+gama0**3*e00)/6.d0
    e04 = ((18.d0*s**2*C0**2-2.d0*gama0*s*C0**2)/(cinf**2)
    & +gama0**4*e00)/24.d0
c........................... 1 left BC
    x = 0.d0 ! String is zero, pre-shock
    p(0) = Pref/Pless
```

```
        print *, 'Pressure Direct',p(0),p(0)*Pless
        rho(0) = rhoref/rholess
c Us = Up*s+C0
        u(0) = Us/cinf
        T(0) = Tref/Tless
        j(0) = rho(0)*u(0)
        ke(0) = rho(0)*u(0)**2/2.d0
        ie(0) = Pref/gama0/Pless ! Mass internal energy
        p(0) = rho(0)*(e01 + 2.d0*e02*x + 3.d0*e03*x**2 + 4.d0*e04*x**3)
        print *, 'Pressure Poly ',p(0),p(0)*Pless
        p(0) = (rhoinf*C0**2
        & *(x + (2.d0*s - gama0/2.d0)*x**2 + s*(3.d0*s - gama0)*x**3))
        & /(rhoinf*cinf**2) + gama0*rho(0)*(ie(0)/rho(0))
        print *, 'Pressure M-G ',p(0),p(0)*Pless
        e(0) = ke(0)+ie(0)
            eta(0) = etainf*(T(0))**w ! Power Law
        print *,'Left B.C. Dimensionless', rho(0),u(0),p(0),T(0),
        & ie(0)/rho(0)
        print *,'Left B.C. Dimensional ', rho(0)*rhoinf,u(0)*cinf,
        &
        &
                (0)*Pless,T(0)*Tless,
                ie(0)*eless/rhoinf
            dsus = 0.d0 ! sum of entropy form stress
            dsu(0) = 0.d0 ! stress entropy term
            dsTs = 0.d0 ! sum of entropy from T
            dsT(0) = 0.d0 ! Temperature entropy term
```




```
c rho(jj) = rho(0)*(gama+1.d0)*Ma**2/((gama-1.d0)*Ma**2+2.d0)
```

c rho(jj) = rho(0)*(gama+1.d0)*Ma**2/((gama-1.d0)*Ma**2+2.d0)
c x = 1.d0 - rho(0)/rho(jj)
c x = 1.d0 - rho(0)/rho(jj)
u(jj) = (Us-Up)/cinf
u(jj) = (Us-Up)/cinf
cx u(jj) = Us-Up
cx u(jj) = Us-Up
c u(jj) = u(0)*(2.d0+(gama0)*Ma**2)/((gama0+2.d0)*Ma**2)
c u(jj) = u(0)*(2.d0+(gama0)*Ma**2)/((gama0+2.d0)*Ma**2)
c u(jj) = rho(0)*u(0)/rho(jj) ! rankine hugoniot jump equations
c u(jj) = rho(0)*u(0)/rho(jj) ! rankine hugoniot jump equations
for stationary Euler shock wave
for stationary Euler shock wave
rho(jj) = rho(0)*u(0)/u(jj)
rho(jj) = rho(0)*u(0)/u(jj)
cx rho(jj) = rhoinf*Us/u(jj)
cx rho(jj) = rhoinf*Us/u(jj)
x = 1.d0 - rho(0)/rho(jj)
x = 1.d0 - rho(0)/rho(jj)
x = 1.d0 - rhoinf/rho(jj)
x = 1.d0 - rhoinf/rho(jj)
p(jj) = rho(0)*u(0)**2 + p(0) - rho(jj)*u(jj)**2
p(jj) = rho(0)*u(0)**2 + p(0) - rho(jj)*u(jj)**2
p(jj) = rhoinf*Us**2 + Pref - rho(jj)*u(jj)**2
p(jj) = rhoinf*Us**2 + Pref - rho(jj)*u(jj)**2
print *,'Pressure Hugoniot', p(jj),p(jj)*Pless
print *,'Pressure Hugoniot', p(jj),p(jj)*Pless
print *, 'pressure hugoniot', p(jj)
print *, 'pressure hugoniot', p(jj)
ie(jj) = (rho(0)*u(0)*(ie(0)/rho(0) + u(0)**2/2.d0 + p(0)/rho(0))
ie(jj) = (rho(0)*u(0)*(ie(0)/rho(0) + u(0)**2/2.d0 + p(0)/rho(0))
\& /(rho(jj)*u(jj)) - u(jj)**2/2.d0 - p(jj)/rho(jj))
\& /(rho(jj)*u(jj)) - u(jj)**2/2.d0 - p(jj)/rho(jj))
\& *rho(jj) ! Mass internal energy
\& *rho(jj) ! Mass internal energy
print *,'Internal Energy Hugoniot',ie(jj),
print *,'Internal Energy Hugoniot',ie(jj),
\& ie(jj)*eless,ie(jj)*eless/(rho(jj)*rhoinf)
\& ie(jj)*eless,ie(jj)*eless/(rho(jj)*rhoinf)
cx ie(jj) = (Cv*Tref/rhoinf+Us**2/2.d0 + Pref/rhoinf
cx ie(jj) = (Cv*Tref/rhoinf+Us**2/2.d0 + Pref/rhoinf
cx \& - u(jj)**2/2.d0 - p(jj)/rho(jj))
cx \& - u(jj)**2/2.d0 - p(jj)/rho(jj))
cx \& *rho(jj) ! Mass internal energy
cx \& *rho(jj) ! Mass internal energy
ie(jj) = (p(jj) - (rho(0)*C0**2
ie(jj) = (p(jj) - (rho(0)*C0**2
c \& *(x+(2.d0*s - gama0/2.d0)*x**2+s*(3.d0*s-gama0)*x**3))

```
c & *(x+(2.d0*s - gama0/2.d0)*x**2+s*(3.d0*s-gama0)*x**3))
```

```
c & /(rhoinf*cinf**2))/gama0/rho(0)
c ie(jj) = ie(jj)*rho(jj)
    print *,'internal energy eos', ie(jj)
    gam0 = 2.d0*(-p(jj) + c0**2/cinf**2*x + 2.d0*x**2*s*C0**2/cinf**2
    & + 3.d0*s**2*x**3*C0**2/cinf**2)
    & /(x**2*C0**2/cinf**2 + 2.d0*x**3*s*C0**2/cinf**2
    & - 2.d0*ie(jj)/rho(jj))
        gam0 = 2.d0*(p(jj) - x-2.d0*x**2*s-3.d0*s**2*x**3)
c gam0 = 2.d0*(p(jj) - x-2.d0****2*s-3.d0*s**2*x**3)
    print *,'M-G Gamma Diff is/was',gam0,gama0
        pause
        gama0 = gam0
        print *,'Values to find pressure'
        print *, 'rho(0)',rho(0)*rhoinf,'C0',
C0,'x',x,'s',s,'gama0',gama0
    print *, 'rhoinf', rhoinf,'cinf', cinf,
    & 'ie(jj)',ie(jj)*eless/(rho(jj)*rhoinf),
    & 'rho(jj)',rho(jj)*rhoinf, 'Pless', Pless, 'eless', eless,
    & 'rhoinf*cinf**2', rhoinf*cinf**2
c p(jj) = -
gama0**5*x**4*e00/(24.d0*cinf**2)+gama0**2****4*s/12.d0
c & - 3.d0*gama0*x**4*s**2/4.d0
    & + (x+(2.d0*s - gama0/2.d0)*x**2 + s*(3.d0*s - gama0)*x**3)
    & + gama0*rho(0)*ie(jj)/rho(jj) ! 4th order eos
    p(jj) = (x + (2.d0*s - gama0/2.d0)*x**2 + s*(3.d0*s - gama0)*x**3)
    & *C0**2/cinf**2 + gama0*ie(jj)/rho(jj) ! 3rd order
eos
            print *, 'Prssure M-G ',p(jj),p(jj)*Pless
c p(jj) = rhoinf*C0**2
c & *(x + (2.d0*s - gama0/2.d0)*x**2 + s*(3.d0*s -
gama0)* x**3)
c & + gama0*ie(jj)*eless/rho(jj)
    print *, 'prssure M-G DN ',p(jj)/Pless,p(jj)
    print *, rho(0), rhoinf
    ke(jj) = rho(jj)*u(jj)**2/2.d0
    e(jj) = ie(jj) + ke(jj)
    T(jj) = T(0) + ie(jj)/rho(jj) - ie(0)/rho(0)
    print *,'Temperature ',T(jj),T(jj)*Tless
    e0 = e00+e01*x+e02*x**2+e03*x**3+e04*x**4
    P0 = rho(0)*(e01+2.d0*e02*x+3.d0*e03*x**2+4.d0*e04*x**3)
    print *, 'P(v) ', P0-gama0*rho(0)*e0
    print *, 'P(T) ', gama0*rho(0)*ie(jj)/rho(jj)
    print *, 'P with Strain', x+(2.d0*s-gama0/2.d0)*x**2
    & +s*(3.d0*s-gama0)*x**3
    print *, 'P with Temp ', gama0*rho(0)*ie(jj)/rho(jj)
c print *,'p0 and p(0)', p0, p(0)
c e0 = e00+e01*x+e02*x**2+e03*x**3+e04*x**4
c print *,'e0 and e(0)', e0, e(0)
c p(jj) = p0 + gama0*rho(0)*(ie(jj)/rho(jj) - e0)
    print *,'prssure changed e0', p(jj), p(jj)*Pless
    print *, 'Right B.C. Dimensionless ',rho(jj),u(jj),p(jj),T(jj),
    &
                                    ie(jj)
```

```
    print *, 'Right B.C. Dimensional ',rho(jj)*rhoinf,u(jj)*cinf,
        &
    & p(jj) Pless,T(jj) Tless,
    & e(jj)*eless/(rho(jj)*rhoinf)
c pause
c eta(jj) = etainf*(T(jj))**w ! power law
    dsu(jj) = 0.d0 ! stress entropy
term
    dsT(jj) = 0.d0 ! T entropy term
        elseif(eos .eq. 2) then
        T(0) = Tinf/Tless
        p(0) = (gama - 1.d0)*T(0)
        rho(0) = 1.d0
        u(0) = Ma
    T(0) = 1.d0
        j(0) = rho(0)*u(0)
        e(0) = rho(0)*u(0)*u(0)/2.d0 + p(0)/(gama-1.d0)
        dsus = 0.d0 ! sum of entropy form stress
        dsu(0) = 0.d0 ! stress entropy term
        dsTs = 0.d0 ! sum of entropy from T
c omegau(0) =
1.16145/((Tinter*T(0))**0.14874) ! Chapman-Enskog
c & + 0.52487/(exp(0.77320*Tinter*T(0)))
c & + 2.16178/(exp(2.43787*Tinter*T(0)))
c eta(0) = 5.0*sqrt(m*k*T(0)/acos(-1.0))/(16.0*omegau(0)*sigma**2)
c eta(0) = 2.0*sqrt(m*k*T(0)/acos(-1.0))/(3.0*acos(-
1.0)*sigma**2) ! Maxwell
    x = T(0)*Tinf/vari0
        eta(0) = etainf*(T(0))**w ! Power Law
    p(jj) = 4.5000*p(0)
    T(jj) = 1.6875*T(0)
    rho(jj) = 2.667*rho(0)
    u(jj) = 0.5774
    j(jj) = rho(jj)*u(jj)
    e(jj) = rho(jj)*u(jj)*u(jj)/2 + p(jj)/(gama-1)
    rho(jj) = rho(0)*(gama+1.d0)*Ma**2/((gama-1.d0)*Ma**2+2.d0)
    u(jj) = u(0)*(2.d0+(gama-1.d0)*Ma**2)/((gama+1.d0)*Ma**2)
    p(jj) = p(0)*(2.d0*gama*Ma**2-gama+1.d0)/(gama+1.d0)
    e(jj) = rho(jj)*u(jj)*u(jj)/2.d0 + p(jj)/(gama-1.d0)
    ie(jj) = p(jj)/(gama - 1.d0)
    T(jj) = p(jj)/(gama - 1.d0)/rho(jj)
    dsu(jj) = 0.d0 ! stress entropy term
    dsT(jj) = 0.d0 ! T entropy term
c Cv0 = ie(jj)/rho(jj)/T(jj)
```

```
c CvD = Cv0*gama*R
c omegau(jj) =1.16145/((Tinter*T(jj))**0.14874) ! Chapman-Enskog
c & + 0.52487/(exp(0.77320*Tinter*T(jj)))
c & + 2.16178/(exp(2.43787*Tinter*T(jj)))
    eta(jj) = 5.0*sqrt(m*k*T(jj)/acos(-1.0))
    & /(16.0*omegau(jj)*sigma**2)
    eta(jj) = 2.0*sqrt(m*k*T(jj)/acos(-1.0))/(3.0*acos(-
1.0)*sigma**2) ! Maxwell
c eta(jj) = eta(0)
c eta(jj) = etainf*(T(jj))**w
c-------------------------------------------------------------------
    elseif(eos .eq. 3) then !M-G LIQUID
    print *, 'Us = ', Us, 'Up = ', Up
c............................LHS BC...........................
    u(0) = Us/cinf
    rho(0) = rhoinf/rhoinf
    p(0) = Pref/Pless
    print *, 'pressure direct', p(0),p(0)*Pless
    T(0) = Tref/Tless
    ke(0) = rho(0)*u(0)*u(0)/2.d0
    ie(0) = p(0)/gama0
    e(0) = ke(0)+ ie(0)
    print *,'left HS DL', rho(0),u(0), p(0), T(0), e(0)
    print *,'left HS DN', rho(0)*rhoinf, u(0)*cinf, p(0)*Pless,
        & T(0)*Tless, e(0)*eless
    dsus = 0.d0 ! sum of entropy form stress
    dsu(0) = 0.d0 ! stress entropy term
    dsTs = 0.d0 ! sum of entropy from T
    dsT(0) = 0.d0 ! T entropy term
c..........................RHS BC
    u(jj)=(Us-Up)/cinf
    rho(jj) = u(0)*rho(0)/u(jj)
    x = 1.d0 - rho(0)/rho(jj)
    p(jj) = p(0) + rho(0)*u(0)**2 - rho(jj)*u(jj)**2
    print *,'pressure hugoniot',p(jj),p(jj)*Pless
    ie(jj) =(rho(0)*u(0)*(ie(0)/rho(0)+u(0)**2/2.d0 + p(0)/rho(0))
    & /(rho(jj)*u(jj)) - u(jj)**2/2.d0 - p(jj)/rho(jj))
    & *rho(jj)
    print *,'internal energy hugoniot',ie(jj),
    & ie(jj)*eless, ie(jj)*eless/(rho(jj)*rhoinf)
    ke(jj) = rho(jj)*u(jj)**2/2.d0
    e(jj) = ie(jj) + ke(jj)
    gam0 = 2.d0*(p(jj)-x-2.d0****2*s-3.d0*s**2*x**3)
    & /(-x**2-2.d0*x**3*s+2.d0*rho(0)*ie(jj)/rho(jj))
    print *,'Gamma diff is/was', gam0, gama0
    gama0 = gam0
    print *,'values to find pressure'
    print *, 'rho(0)',rho(0)*rhoinf,'C0',
C0,'x',x,'s',s,'gama0',gama0
```

```
        print *, 'rhoinf', rhoinf,'cinf', cinf,
    & 'ie(jj)',ie(jj)*eless/(rho(jj)*rhoinf),
    & 'rho(jj)',rho(jj)*rhoinf, 'Pless', Pless, 'eless', eless,
    & 'rhoinf*cinf**2', rhoinf*cinf**2
c p(jj) = -
gama0**5*x**4*e00/(24.d0*cinf**2)+gama0**2****4*s/12.d0
c & - 3.d0*gama0*x**4*s**2/4.d0
c & + (x+(2.d0*s - gama0/2.d0)****2 + s*(3.d0*s - gama0)* x**3)
c & + gama0*rho(0)*ie(jj)/rho(jj) ! 4th order eos
    p(jj) = (x + (2.d0*s - gama0/2.d0)* X**2 + s*(3.d0*s - gama0)*x**3)
    & + gama0*rho(0)*ie(jj)/rho(jj) ! 3rd order eos
    print *, 'prssure M-G DL ',p(jj), p(jj)*Pless
    T(jj) = T(0) + ie(jj)/rho(jj) - ie(0)/rho(0)
    print *,'Temp DL', T(jj), T(jj)*Tless
    print *, 'right HS DL', rho(jj),u(jj),p(jj),T(jj),e(jj)
    print *, 'right HS DN', rho(jj)*rhoinf,u(jj)*cinf,p(jj)*Pless,
    & T(jj)*Tless,e(jj)*eless
c pause
    dsu(jj) = 0.d0 ! stress entropy term
    dsT(jj) = 0.d0 ! T entropy term
    endif
c----------------------printout jump condition--------------------
    print *,'Jump Conditions'
c Print *,'dimensional Tem',T(0)*cinf**2/Cv
c Print *, T(jj)*cinf**2/Cv, T(jj)
c Print *,'Tem and InterE', T(0),ie(0)/rho(0),T(jj),ie(jj)/rho(jj)
    Print *,'Velocity ratio ',u(jj)/u(0)
    print *,'Temperature ratio ',T(jj)/T(0)
    print *,'Density ratio ',rho(jj)/rho(0)
    Print *,'Pressure ratio ',p(jj)/p(0)
    print *,'Velocity Dimensional ',u(0)*cinf,u(jj)*cinf
    Pause
c........update heat conductivity to calculate entropy (GAS Only)....
        if (eos .ne. 3) then
        kappa0 = gama*R*eta(0)/((gama-1.d0)*Pr*Cv)
        kappa = kappa0*(Cv*rhoinf*cinf*lambda)
        endif
c-------------------------theoretical entropy-----------------------
c e(jj) =(rho(0)*u(0)*(ie(0)/rho(0)+u(0)** print *, log(2.d0)
    dsa = Cv*dlog(T(jj)/T(0))+ R*dlog(rho(0)/rho(jj)) ! J/kg.k
theoretical Entropy
    print *,Cv,Cv*dlog(T(jj)/T(0))
    print *,R,R*dlog(rho(0)/rho(jj))
    print *,dsa
    pause
    omegau = 1.16145/(vari0*T(jj))**0.14874
```

```
c & + 0.52487/(exp(0.77320*vari0*T(jj)))
c & + 2.16178/(exp(2.43787*vari0*T(jj)))
c x = T(jj)*Tinf/vari0
c omegau = -0.0799*x**5 + 0.743*x**4 - 2.7973*x**3 + 5.485*x**2
c & -5.9588*x + 4.1996
c eta(jj) = 5.0*sqrt(acos(-1.0)*m*k*T(jj))/
c & ((16.0*acos(-1.0)*sigma**2*omegau)*(rhoinf*cinf*lambda))
c etad(jj) = 5.0*sqrt(acos(-1.0)*m*k*T(jj))/
c & (16.0*acos(-1.0)*sigma**2*omegau)
c eta(jj) = etad(jj)/(rhoinf*cinf*lambda)
C
    eta(jj) = etainf*(T(jj))**w
```

```
c-----------------------set initial condidion
```

c-----------------------set initial condidion
c.........................Left Half
c.........................Left Half
do i = 1,jj/2
do i = 1,jj/2
rho(i) = rho(0)
rho(i) = rho(0)
T(i) = T(0)
T(i) = T(0)
u(i) = u(0)
u(i) = u(0)
p(i) = p(0)
p(i) = p(0)
j(i) = u(i)*rho(i)
j(i) = u(i)*rho(i)
e(i) = e(0)
e(i) = e(0)
eta(i) = eta(0)
eta(i) = eta(0)
! write (*,'(i4,f12.5)') i,T(i)
! write (*,'(i4,f12.5)') i,T(i)
enddo
enddo
c.........................Right Half.............................
do i=jj/2,jj-1
rho(i) = rho(jj)
T(i) = T(jj)
u(i) = u(jj)
p(i) = p(jj)
j(i) = rho(i)*u(i)
e(i) = e(jj)
eta(i) = eta(jj)
! write (*,'(i4,f12.5)') i,t(i)
enddo
C
print *,'RH',p(jj)/p(0),rho(jj)/rho(0),u(jj)/u(0),T(jj)/T(0)
print *,eta(0)
c pause
C
do i=0,jj
write(*,'(A2,i5,10f10.3)')
\& 'IC',i,rho(i),u(i),p(i),t(i),e(i),p(i)
C----------------------------------------------------------------------------
c read restart file
c----------------------------------------------------------------------------
nstep = 0
ans='n'
if (ans .eq. 'y' .or. ans .eq. 'Y') then

```
```

c read in old file
open (unit=44, file='restart.dat',form='formatted',
\& status='old',err=135)
do i = 0,jj,1 !Zero out variables
read(44,'(i15,6e25.18)') nstep,rho(i),U(i),P(i),e(i),T(i),eta(i)
c write(*,'(6e25.18)') rho(i),U(i),P(i),e(i),T(i),eta(i)
rhohat(i) = rho(i)
uhat(i) = u(i)
phat(i) = p(i)
ehat(i) = e(i)
enddo
print *,'ShockLeft:',rho(0),u(0),p(0),e(0),T(0)
print *,'ShockRigh: ',rho(jj),u(jj),p(jj),e(jj),T(jj)
print *,'ShockJump: ',
\& rho(jj)/rho(0),u(jj)/u(0),p(jj)/p(0),e(jj)/e(0),t(jj)/t(0)
print *,'*'
goto 137
Print *,'No *restart file...'
close(44)
if (1 .eq. 1) then ! average out a restart
do i=0,jj-2,2
rho(i+1) = (rho(i+2) + rho(i))/2.d0
u(i+1) = (u(i+2) + u(i))/2.d0
p(i+1) = (p(i+2) + p(i))/2.d0
e(i+1) = (e(i+2) + e(i))/2.d0
eta(i+1) = (eta(i+2) + eta(i))/2.d0
enddo
c flag = .false.
endif
goto 456
endif
c-------------------- state time steps
456 do n = nstep+1,nstep+1000000 !time
c----------------------shock move-------------------------------
if (eos .eq. 0) then ! ideal gas EOS
umax = 0.
do i = 0,jj
uloc = abs(u(i))+dsqrt(T(i))
if (uloc .gt. umax) umax=uloc
enddo
ht = 0.001*hx/uloc
c print *,'ht=',ht
c print *,'integer time ',n
do i= 0,jj-2,2 !space
c calculate average
j(i+1) = (rho(i+2)*u(i+2) + rho(i)*u(i))/2.d0
PI(i+1) = 4.d0*(eta(i+2)+ eta(i))*(u(i+2)-u(i))/hx/6.d0
q(i+1) = -1.d0*(eta(i+2)+ eta(i))*(T(i+2)-T(i))/hx
\& /((gama-1.d0)*Pr)/2.d0
c T(i+1) = gama*p(i+1)/rho(i+1)
E(i) = rho(i)*u(i)*u(i)/2.d0+p(i)/(gama-1.d0)
rho(i+1) = (rho(i+2)+ rho(i))/2.d0

```
```

u(i+1) = (u(i+2)+u(i))/2.d0
p(i+1) = (p(i+2)+ p(i))/2.d0
E(i+1) = (E(i+2)+ E(i))/2.d0
H(i+1) = (E(i+1)+p(i+1))/rho(i+1)

```
c omegau \(=1.16145 /(\) vari0*T(i))**0.14874
C
    enddo
    do \(i=0, j j\)
    write(*,'(i4,10f10.3)')
    \& \(i, j(i), P I(i), q(i), T(i), E(i), r h o(i), u(i), p(i), e(i), h(i)\)
    enddo
    print *,'1',n,rho(24)
    do i=2,jj-2,2
    \(q(i)=(q(i-1)+q(i+1)) / 2 . d 0\)
    rhohat(i)=rho(i)-ht*(j(i+1)-j(i-1))/hx
    jhat(i) \(=\) rho(i)*u(i) +ht*( \((P I(i+1)-P I(i-1))\)
\&
\&
    Ehat(i) \(=E(i)+h t^{*}(((P I(i+1) * u(i+1))-P I(i-1) * u(i-1))-\)
\& \(\quad(j(i+1) * H(i+1) \quad-\quad j(i-1) * H(i-1))-\)
\& \((q(i+1) \quad-\quad q(i-1))) / h x\)
uhat(i) \(=\) jhat(i)/rhohat(i)
    phat (i) \(=(\) gama \(-1 . d 0) *(E h a t(i)-r h o h a t(i) * u h a t(i) * u h a t(i) / 2 . d 0)\)
    enddo
    do \(i=0, j j\)
    write(*,'(i4,10f10.3)')
    \& \(i, \operatorname{rhohat}(i), j \operatorname{hat}(i), \operatorname{ehat}(i), \operatorname{phat}(i)\), uhat(i)
    enddo
    print *, rho(24),ht,j(28+1),j(28-1),hx
    print *,'2', n, rhohat(28)
    do \(i=2, j j-2,2\)
    rho(i) = rhohat(i)
    u(i) = uhat(i)
    \(j(i)=j h a t(i)\)
    \(E(i)=\) Ehat \((i)\)
    \(p(i)=p h a t(i)\)
    T(i) \(=\) gama*p(i)/rho(i)
\& \(\quad+0.52487 \mathrm{~d} 0 /(\exp (0.77320 d 0 * T i n t e r * T(i)))\)
\& \(+2.16178 d 0 /(\exp (2.43787 d 0 * T i n t e r * T(i)))\)
    eta(i) \(=5 . d 0 * d s q r t\left(m^{*} k^{*} T(i) / a \cos (-1 . d 0)\right)\)
\& \(/(16 . d 0 * o m e g a u(i) *\) sigma**2)
    eta(i) \(=2 . d 0 * d s q r t(m * k * T(i) / a c o s(-1 . d 0))\)
    \& \(/\left(3 . d 0^{*} \operatorname{acos}(-1 . d 0) *\right.\) sigma**2) ! Maxwell
    \& \(\quad+0.52487 /\left(\exp \left(0.77320^{*} \operatorname{vari} 0^{*} T(i)\right)\right)\)
                    \(-(j(i+1) * u(i+1)-j(i-1) * u(i-1))\)
                                    \(-(p(i+1)-p(i-1))) / h x\)
    omegau(i) = 1.16145d0/((Tinter*T(i))**0.14874d0) ! Chapman-Enskog
```

c \& + 2.16178/(exp(2.43787*vari0*T(i)))
c eta(i) = 5.0*sqrt(acos(-1.0)*m*k*T(i))/
c \& ((16.0*acos(-1.0)*sigma**2*omegau)*(rhoinf*cinf*lambda))
x = T(i)*Tinf/vari0
omegau = -0.0799*x**5 + 0.743*x**4 - 2.7973*x**3 + 5.485*x**2
\& -5.9588*x + 4.1996
etad(i) = 5.d0*dsqrt(acos(-1.0)*m*k*T(i))/
\& ((16.d0*acos(-1.0)*sigma**2*omegau)*(rhoinf*cinf*lambda))
eta(i) = etad(i)/(rhoinf*cinf*lambda)
etad(i) = 5.0*sqrt(acos(-1.0)*m*k*T(i))/
\& (16.0*acos(-1.0)*sigma**2*omegau)
eta(i) = etad(i)/(rhoinf*cinf*lambda)
eta(i) = etainf*(T(i))**w ! Power Law
enddo
c print *,'3',n,rho(28)
c do i=0,jj-2,2
c rho(i+1) = (rho(i+2)+rho(i))/2.0
c u(i+1) = (u(i+2)+u(i))/2.0
c p(i+1) = (p(i+2)+p(i))/2.000
c E(i+1) = (E(i+2)+E(i))/2.0
c H(i+1) = (E(i+1)+p(i+1))/rho(i+1)
c enddo
c do i=0,jj
write(*,'(A1,i4,10f10.3)')
\& 'e',i,rho(i),j(i),e(i),p(i),u(i)
enddo
print *,'4',n,rho(28)
elseif (eos .eq. 4) then ! ideal gas EOS with general Dless
scales
umax = 0.
do i = 0,jj
uloc = abs(u(i))+dsqrt(gama*(gama-1.d0)*T(i))
if (uloc .gt. umax) umax=uloc
enddo
ht = 0.001*hx/uloc
c print *,'ht=',ht
c print *,'integer time ',n
do i= 0,jj-2,2 !space
c calculate average
j(i+1) = (rho(i+2)*u(i+2) + rho(i)*u(i))/2.d0
PI(i+1) = 4.d0*(eta(i+2)+ eta(i))*(u(i+2)-u(i))/hx/6.d0
q(i+1) = -1.d0*gama*(eta(i+2)+ eta(i))*(T(i+2)-T(i))/hx
\& /(Pr)/2.d0
c T(i+1) = gama*p(i+1)/rho(i+1)

```
```

    \(E(i)=r h o(i) * u(i) * u(i) / 2 . d 0+p(i) /(g a m a-1 . d 0)\)
    rho(i+1) \(=(r h o(i+2)+r h o(i)) / 2 . d 0\)
    \(u(i+1)=(u(i+2)+u(i)) / 2 . d 0\)
    \(p(i+1)=(p(i+2)+p(i)) / 2 . d 0\)
    \(E(i+1)=(E(i+2)+E(i)) / 2 . d 0\)
    \(H(i+1)=(E(i+1)+p(i+1)) / r h o(i+1)\)
    C
c do i=0,jj
write(*,'(i4,10f10.3)')
\& $i, j(i), P I(i), q(i), T(i), E(i), r h o(i), u(i), p(i), e(i), h(i)$
enddo
print *,'1', n, rho(24)
do i=2,jj-2,2
$q(i)=(q(i-1)+q(i+1)) / 2 . d 0$
rhohat(i)=rho(i)-ht*(j(i+1)-j(i-1))/hx
jhat(i) $=$ rho(i)*u(i) $+h t^{*}(P I(i+1)-P I(i-1))$
\& $\quad-(j(i+1) * u(i+1)-j(i-1) * u(i-1))$
\& $-(p(i+1)-p(i-1))) / h x$
Ehat(i) $=E(i)+h t *((P I(i+1) * u(i+1))-P I(i-1) * u(i-1))-$
\& $\quad(j(i+1) * H(i+1) \quad-j(i-1) * H(i-1))-$
\& $(q(i+1) \quad-\quad q(i-1))) / h x$
uhat(i) $=$ jhat(i)/rhohat(i)
phat(i) $=$ (gama $-1 . d 0$ )*(Ehat(i)-rhohat(i)*uhat(i)*uhat(i)/2.d0)
C
enddo
do $i=0, j j$
write(*,'(i4,10f10.3)')
\& i, rhohat(i),jhat(i), ehat(i), phat(i), uhat(i)
enddo
print *, rho(24),ht,j(28+1), j(28-1), hx
print *,'2', n, rhohat(28)
do i=2,jj-2,2
rho(i) $=$ rhohat(i)
u(i) = uhat(i)
$j(i)=j h a t(i)$
E(i) = Ehat(i)
p(i) = phat(i)
T(i) $=p(i) / r h o(i) /(g a m a-1 . d 0)$
c omegau(i) $=1.16145 \mathrm{~d} 0 /(($ Tinter*T(i))**0.14874d0)
Chapman-Enskog

```

```

        omegau = 1.16145/(vari0*T(i))**0.14874
    \& + 0.52487/(exp(0.77320*vari0*T(i)))
\& + 2.16178/(exp(2.43787*vari0*T(i)))
eta(i) = 5.0*sqrt(acos(-1.0)*m*k*T(i))/
\& ((16.0*acos(-1.0)*sigma**2*omegau)*(rhoinf*cinf*lambda))
x = T(i)*Tinf/vari0
omegau = -0.0799*x**5 + 0.743*x**4 - 2.7973*x**3 + 5.485****2
\& -5.9588*x + 4.1996
etad(i) = 5.d0*dsqrt(acos(-1.0)*m*k*T(i))/
\& ((16.d0*acos(-1.0)*sigma**2*omegau)*(rhoinf*cinf*lambda))
eta(i) = etad(i)/(rhoinf*cinf*lambda)
etad(i) = 5.0*sqrt(acos(-1.0)*m*k*T(i))/
\& (16.0*acos(-1.0)*sigma**2*omegau)
eta(i) = etad(i)/(rhoinf*cinf*lambda)
eta(i) = etainf*(T(i))**w ! Power Law
enddo
print *,'3',n,rho(28)
do i=0,jj-2,2
rho(i+1) = (rho(i+2)+rho(i))/2.0
u(i+1) = (u(i+2)+u(i))/2.0
p(i+1) = (p(i+2)+p(i))/2.000
E(i+1) = (E(i+2)+E(i))/2.0
H(i+1) = (E(i+1)+p(i+1))/rho(i+1)
enddo

```
    do \(i=0, j j\)
        write(*,'(A1, i4,10f10.3)')
        \& 'e',i,rho(i), \(j(i), e(i), p(i), u(i)\)
        enddo
    print *,'4', n, rho(28)
    elseif (eos .eq. 1) then ! M-G EOS
    umax \(=0 . d 0\)
    do i \(=0, j j\)
    uloc = abs(u(i))+dsqrt((gama0+1.d0)*gama0*T(i))
    if (uloc .gt. umax) umax=uloc
    enddo
    ht \(=0.001^{* h x / u l o c ~}\)
    print *,'ht=',ht
    print *,'integer time ', n
    do \(i=0, j j-2,2\) !space
c calculate average
    \(j(i+1)=(r h o(i+2) * u(i+2)+r h o(i) * u(i)) / 2 . d 0\)
```

        PI(i+1) = 4.d0*(eta(i+2)+ eta(i))*(u(i+2)-u(i))/hx/6.d0
        q(i+1) = -1.d0*(gama0+1.d0)*(eta(i+2)+ eta(i))*
        & (T(i+2)-T(i))/(hx*Pr*2.d0)
        q(i+1) = - kappa0*(T(i+2)-T(i))/hx
    q(i+1) = - (eta(i+2)+ eta(i))*(T(i+2)-T(i))/hx/((gama0)*Pr)/2.d0
        T(i+1) = gama*p(i+1)/rho(i+1)
        E(i) = rho(i)*u(i)*u(i)/2.d0+p(i)/gama0
        rho(i+1) = (rho(i+2)+ rho(i))/2.d0
        u(i+1) = (u(i+2)+u(i))/2.d0
        p(i+1) = (p(i+2)+p(i))/2.d0
        E(i+1) = (E(i+2)+ E(i))/2.d0
        H(i+1) = (E(i+1)+ p(i+1))/rho(i+1)
        enddo
    do i=0,jj
    write(*,'(i4,10f10.3)')
    & i,j(i),PI(i),q(i),T(i),E(i),rho(i),u(i),p(i),e(i),h(i)
        enddo
    print *,'1',n,rho(24)
        do i=2,jj-2,2
        q(i) = (q(i-1)+q(i+1))/2.d0
        rhohat(i)=rho(i)-ht*(j(i+1)-j(i-1))/hx
        jhat(i) = rho(i)*u(i) + ht*( (PI(i+1) - PI(i-1))
        & -(j(i+1)*u(i+1) - j(i-1)*u(i-1))
        & -(p(i+1) - p(i-1)))/hx
        Ehat(i) = E(i)+ ht*(((PI(i+1)*u(i+1)) - PI(i-1)*u(i-1))-
        & (j(i+1)*H(i+1) - j(i-1)*H(i-1))-
        & (q(i+1) - q(i-1)))/hx
        uhat(i) = jhat(i)/rhohat(i)
        x = 1.d0 - rho(0)/rhohat(i)
    c phat(i) = -
gama0**5*x**4*e00/(24.d0*cinf**2)+gama0**2*x**4*s/12.d0
c \& - 3.d0*gama0*x**4*s**2/4.d0
c \& + (x + (2.d0*s- gama0/2.d0)*x**2 + s*(3.d0*s -
gama0)*x**3)
c \& + gama0*rho(0)*(Ehat(i)-rhohat(i)*uhat(i)**2/2.d0)
c \& /rhohat(i) ! 4th order eos
phat(i) = (x + (2.d0*s - gama0/2.d0)*x**2
\& + s*(3.d0*s - gama0)*x**3)*C0**2/cinf**2
\& + gama0*rho(0)*(Ehat(i)-rhohat(i)*uhat(i)**2/2.d0)
\& /rhohat(i) ! 3rd order eos
print *,'values to find pressure'
print *, 'rho(0)',rho(0),'x',x,'s',s,'gama0',gama0
print *, 'rhohat',rhohat(i),'Ehat',Ehat(i),'uhat(i)',uhat(i)
print *, 'phat(i)', phat(i)
pause
phat(i) = gama0*((Ehat(i)-rhohat(i)*uhat(i)**2/2.d0)
phat(i) = p(0)
\& + gama0*rho(0)*((Ehat(i)-rhohat(i)*uhat(i)**2/2.d0)
\& /rhohat(i)

```
```

c \& - ie(0)/rho(0))
c phat(i) = gama0*rhoref*(Ehat(i)-rhohat(i)*uhat(i)*uhat(i)/2.0
c \& - eref) + Pref
phat(i)= gama0*(Ehat(i)-rhohat(i)*uhat(i)*uhat(i)/2.0)
enddo
if (n/100 .eq. float(n)/100.) then
do bug = 0,jj,10 !debug
write (*,'(2i5,3f16.5)')n,bug, phat(bug), Ehat(bug),rhohat(bug)
enddo
pause
endif
do i=0,jj
write(*,'(i4,10f10.3)')
\& i,rhohat(i),jhat(i),ehat(i),phat(i),uhat(i)
enddo
print *,rho(24),ht,j(28+1),j(28-1),hx
print *,'2',n,rhohat(28)
do i=2,jj-2,2
rho(i) = rhohat(i)
u(i) = uhat(i)
j(i) = jhat(i)
E(i) = Ehat(i)
p(i) = phat(i)
T(i) = T(0)+ (E(i)-rho(i)*u(i)**2/2.d0)/rho(i)
\& - (E(0)-rho(0)*u(0)**2/2.d0)/rho(0)
PI(i) = 4.d0*eta(i)*(u(i+2)-u(i))/2.d0/hx/3.d0
omegau(i) =
1.16145/((Tinter*T(i))**0.14874) ! Chapman-Enskog
c \& + 0.52487/(exp(0.77320*Tinter*T(i)))
c \& + 2.16178/(exp(2.43787*Tinter*T(i)))
eta(i) = 5.0*sqrt(m*k*T(i)/acos(-1.0))/(16.0*omegau(i)*sigma**2)
eta(i) = 2.0*sqrt(m***T(i)/acos(-1.0))/(3.0*acos(-
1.0)*sigma**2) ! Maxwell
omegau = 1.16145/(vari0*T(i))**0.14874
\& + 0.52487/(exp(0.77320*vari0*T(i)))
\& + 2.16178/(exp(2.43787*vari0*T(i)))
eta(i) = 5.0*sqrt(acos(-1.0)*m*k*T(i))/
\& ((16.0*acos(-1.0)*sigma**2*omegau)*(rhoinf*cinf*lambda))
x = T(i)*Tinf/vari0
omegau = -0.0799*x**5 + 0.743*x**4 - 2.7973*x**3 + 5.485****2
\& -5.9588*x + 4.1996
etad(i) = 5.0*sqrt(acos(-1.0)*m*k*T(i))/
\& (16.0*acos(-1.0)*sigma**2*omegau)
eta(i) = etad(i)/(rhoinf*cinf*lambda)
eta(i) =
etainf*(T(i))**w
! Power Law
enddo

```
```

C
c print *,'3',n,rho(28)
c do i=0,jj-2,2
c rho(i+1) = (rho(i+2)+rho(i))/2.0
u(i+1) = (u(i+2)+u(i))/2.0
p(i+1) = (p(i+2)+ p(i))/2.0
E(i+1) = (E(i+2)+E(i))/2.0
H(i+1) = (E(i+1)+p(i+1))/rho(i+1)
enddo
do i=0,jj
write(*,'(A1,i4,10f10.3)')
\& 'e',i,rho(i),j(i),e(i),p(i),u(i)
enddo
print *,'4',n,rho(28)
elseif (eos .eq. 2) then ! ideal gas EOS general dimensionless
umax = 0.
do i = 0,jj
uloc = abs(u(i))+dsqrt(gama*R*T(i)/Cv)
if (uloc .gt. umax) umax=uloc
enddo
ht = 0.001*hx/uloc
c print *,'ht=',ht
c print *,'integer time ',n
do i= 0,jj-2,2 !space
c calculate average
j(i+1) = (rho(i+2)*u(i+2) + rho(i)*u(i))/2.d0
PI(i+1) = 4.d0*(eta(i+2)+ eta(i))*(u(i+2)-u(i))/hx/6.d0
q(i+1) = - kappa0*(T(i+2)-T(i))/hx
q(i+1) = - (eta(i+2)+ eta(i))*(T(i+2)-T(i))/hx/((gama0)*Pr)/2.0
c
E(i) = rho(i)*u(i)*u(i)/2.d0+p(i)/gama0
rho(i+1) = (rho(i+2)+ rho(i))/2.d0
u(i+1) = (u(i+2)+u(i))/2.d0
p(i+1) = (p(i+2)+ p(i))/2.d0
E(i+1) = (E(i+2)+E(i))/2.d0
H(i+1) = (E(i+1)+p(i+1))/rho(i+1)
enddo
do i=0,jj
write(*,'(i4,10f10.3)')
\& i,j(i),PI(i),q(i),T(i),E(i),rho(i),u(i),p(i),e(i),h(i)
enddo
print *,'1',n,rho(24)
do i=2,jj-2,2
C
q(i) = (q(i-1)+q(i+1))/2.d0
rhohat(i)=rho(i)-ht*(j(i+1)-j(i-1))/hx
jhat(i) = rho(i)*u(i) + ht*( (PI(i+1) - PI(i-1))

```
```

    &
    & (i)
                -(j(i+1)*u(i+1) - j(i-1)*u(i-1))
    Ehat(i) = E(i)+ ht*(((PI(i+1)*u(i+1)) - PI(i-1)*u(i-1))-
    \& (j(i+1)*H(i+1) - j(i-1)*H(i-1))-
\& (q(i+1) - q(i-1)))/hx
uhat(i) = jhat(i)/rhohat(i)
phat(i)= (gama -1.d0)*(Ehat(i)-rhohat(i)*uhat(i)*uhat(i)/2.d0)
phat(i) = gama0*rhoref*(Ehat(i)-rhohat(i)*uhat(i)*uhat(i)/2.0
\& - eref) + Pref
phat(i)= gama0*(Ehat(i)-rhohat(i)*uhat(i)*uhat(i)/2.0)
if (n/100 .eq. float(n)/100.) then
do bug = 0,jj,10 !debug
write (*,'(2i4,f12.5)')n,bug, phat(bug)
enddo
pause
endif
enddo
do i=0,jj
write(*,'(i4,10f10.3)')
\& i,rhohat(i),jhat(i),ehat(i),phat(i),uhat(i)
enddo
print *,rho(24),ht,j(28+1),j(28-1),hx
print *,'2',n,rhohat(28)
do i=2,jj-2,2
rho(i) = rhohat(i)
u(i) = uhat(i)
j(i) = jhat(i)
E(i) = Ehat(i)
p(i) = phat(i)
T(i) = p(i)/rho(i)/(gama-1.d0)
T(i) = T(0)+ (e(i)-rho(i)*u(i)**2/2.d0)/rho(i)
\& - (e(0)-rho(0)*u(0)**2/2.d0)/rho(0)
omegau(i) =
1.16145/((Tinter*T(i))**0.14874)! Chapman-Enskog
c \& + 0.52487/(exp(0.77320*Tinter*T(i)))
c \& + 2.16178/(exp(2.43787*Tinter*T(i)))
eta(i) = 5.0*sqrt(m* ** T(i)/acos(-1.0))/(16.0*omegau(i)*sigma**2)
eta(i) = 2.0*sqrt(m*k*T(i)/acos(-1.0))/(3.0*acos(-
.0)*sigma**2) ! Maxwell
omegau = 1.16145/(vari0*T(i))**0.14874
\& + 0.52487/(exp(0.77320*vari0*T(i)))
\& + 2.16178/(exp(2.43787*vari0*T(i)))
eta(i) = 5.0*sqrt(acos(-1.0)*m*k*T(i))/
\& ((16.0*acos(-1.0)*sigma**2*omegau)*(rhoinf*cinf*lambda))
x = T(i)*Tinf/vari0
omegau = -0.0799*x**5 + 0.743*x**4 - 2.7973*x**3 + 5.485*x**2
\& -5.9588*x + 4.1996
etad(i) = 5.0*sqrt(acos(-1.0)*m*k*T(i))/
\& (16.0*acos(-1.0)*sigma**2*omegau)

```
```

c eta(i) = etad(i)/(rhoinf*cinf*lambda)
c eta(i) =
etainf*(T(i))**w ! Power Law
enddo
C
c print *,'3',n,rho(28)
c do i=0,jj-2,2
c rho(i+1) = (rho(i+2)+rho(i))/2.0
c u(i+1) = (u(i+2)+u(i))/2.0
c p(i+1) = (p(i+2)+ p(i))/2.0
c E(i+1) = (E(i+2)+E(i))/2.0
c H(i+1) = (E(i+1)+p(i+1))/rho(i+1)
c enddo
c do i=0,jj
c write(*,'(A1,i4,10f10.3)')
c \& 'e',i,rho(i),j(i),e(i),p(i),u(i)
C enddo
C
c print *,'4',n,rho(28)
c---------------------------------------------------------------------
elseif (eos .eq. 3) then !liquid M-G
umax = 0.
do i = 0,jj
c uloc = abs(u(i))+dsqrt(gama*R*T(i)/Cv)
uloc = abs(u(i))+1.d0
if (uloc .gt. umax) umax=uloc
enddo
ht = 0.001*hx/uloc
c print *,'ht=',ht
c print *,'integer time ',n
do i= 0,jj-2,2 !space
c calculate average
j(i+1) = (rho(i+2)*u(i+2) + rho(i)*u(i))/2.d0
PI(i+1) = (4.d0/3.d0+uv)*((eta(i+2)+ eta(i))/2.d0)
\& *(u(i+2)-u(i))/hx
q(i+1) = -kappa0*(T(i+2)-T(i))/hx
rho(i+1) = (rho(i+2)+ rho(i))/2.d0
u(i+1) = (u(i+2)+u(i))/2.d0
p(i+1) = (p(i+2)+p(i))/2.d0
E(i+1) = (E(i+2)+E(i))/2.d0
H(i+1) = (E(i+1)+ p(i+1))/rho(i+1)
c if (n/1000 .eq. float(n)/1000.) then !debug
c print *,'debug',n,E(i)
c endif
enddo

```
```

c print *,Pr, gama, mu, R, Tinf, rhoinf, cinf,lambda,eta(0)
c print *, kappa0,eta(0)/((gama-1.d0)*Pr)
c
do i=2,jj-2,2
C
q(i) = (q(i-1)+q(i+1))/2.d0
rhohat(i)=rho(i)-ht*(j(i+1)-j(i-1))/hx
jhat(i) = rho(i)*u(i) + ht*( (PI(i+1) - PI(i-1))
\& -(j(i+1)*u(i+1) - j(i-1)*u(i-1))
\& -(p(i+1) - p(i-1)))/hx
Ehat(i) = E(i)+ ht*(((PI(i+1)*u(i+1)) - PI(i-1)*u(i-1))-
\& (j(i+1)*H(i+1) - j(i-1)*H(i-1))-
\& (q(i+1) - q(i-1)))/hx
uhat(i) = jhat(i)/rhohat(i)
x = 1.d0 - rho(0)/rhohat(i)
c phat(i) = -
gama0**5****4*e00/(24.d0*cinf**2)+gama0**2* ***4*s/12.d0
c \& - 3.d0*gama0*x**4*s**2/4.d0
c \& + (x + (2.d0*s- gama0/2.d0)*x**2 + s*(3.d0*s -
gama0)*x**3)
c \& + gama0*rho(0)*(Ehat(i)-rhohat(i)*uhat(i)**2/2.d0)
c \& /rhohat(i) ! 4th order eos
phat(i) = (x + (2.d0*s - gama0/2.d0)*x**2 + s*(3.d0*s-gama0)*x**3)
\& + gama0*rho(0)*(Ehat(i)-rhohat(i)*uhat(i)**2/2.d0)
\& /rhohat(i) ! 3rd order eos
print *,'values to find pressure'
print *, 'rho(0)',rho(0),'x',x,'s',s,'gama0',gama0
print *, 'rhohat',rhohat(i),'Ehat',Ehat(i),'uhat(i)',uhat(i)
print *, 'phat(i)', phat(i)
pause
phat(i) = gama0*((Ehat(i)-rhohat(i)*uhat(i)**2/2.d0)
phat(i) = p(0)
\& + gama0*rho(0)*((Ehat(i)-rhohat(i)*uhat(i)**2/2.d0)
\& /rhohat(i)
\& - ie(0)/rho(0))
phat(i) = gama0*rhoref*(Ehat(i)-rhohat(i)*uhat(i)*uhat(i)/2.0
\& - eref) + Pref
phat(i)= gama0*(Ehat(i)-rhohat(i)*uhat(i)*uhat(i)/2.0)
if (n/100 .eq. float(n)/100.) then
do bug = 0,jj,10 !debug
write (*,'(2i4,f12.5)')n,bug, phat(bug)
enddo
pause
endif
enddo
do i=0,jj
write(*,'(i4,10f10.3)')
\& i,rhohat(i),jhat(i),ehat(i),phat(i),uhat(i)
enddo
c

```
```

c print *,rho(24),ht,j(28+1),j(28-1),hx
c print *,'2',n,rhohat(28)
do i=2,jj-2,2
rho(i) = rhohat(i)
u(i) = uhat(i)
j(i) = jhat(i)
E(i) = Ehat(i)
p(i) = phat(i)
T(i) = T(0)+ (e(i)-rho(i)*u(i)**2/2.d0)/rho(i)
\&
- (e(0)-rho(0)*u(0)**2/2.d0)/rho(0)
enddo

```
```

    do i=0,jj
    ```
    do i=0,jj
    write(*,'(A1,i4,10f10.3)')
    write(*,'(A1,i4,10f10.3)')
    & 'e',i,rho(i),j(i),e(i),p(i),u(i)
    & 'e',i,rho(i),j(i),e(i),p(i),u(i)
    enddo
    enddo
    endif
    endif
    if (n/10000 .eq. float(n)/10000.) then
    print *,'Time step n=',n
    if (n .gt. 99 .and. n .le. 999) then
    write(filen(8:10),'(i3)') n
    elseif (n .gt. 999 .and. n .le. 9999) then
    write(filen(7:10),'(i4)') n
    elseif (n .gt. 9999 .and. n .le. 99999) then
    write(filen(6:10),'(i5)') n
    elseif (n .gt. 99999 .and. n .le. 999999) then
    write(filen(5:10),'(i6)') n
    elseif (n .gt. 999999 .and. n .le. 9999999) then
    write(filen(4:10),'(i7)') n
    open(unit=22,file=filen,form='formatted',status='unknown')
    do i=0,jj
    write (22,'(81f12.5)') (hx/2.d0)*(float(i)-float(jj)/2.d0),
    & p(i),rho(i),(rho(i)-rho(0))/(rho(jj)-rho(0))
    enddo
    close(22)
    write(entropy(4:10),'(i7)') n
    elseif (n .gt. 9999999 .and. n .le. 99999999) then
    write(filen(3:10),'(i8)') n
    open(unit=22,file=filen, form='formatted',status='unknown')
    do i=0,jj
    write (22,'(81f12.5)') (hx/2.d0)*(float(i)-float(jj)/2.d0),
    & p(i),rho(i),(rho(i)-rho(0))/(rho(jj)-rho(0))
        enddo
    close(22)
    write(entropy(3:10),'(i8)') n
    endif
    open(unit=22,file=filen,form='formatted',status='unknown')
    print *,'Time step n=',n
    do i=0,jj
    write (22,'(81f12.5)') (hx/2.d0)*(float(i)-float(jj)/2.d0),
```

```
    & p(i),rho(i),(rho(i)-rho(0))/(rho(jj)-rho(0))
```

    & p(i),rho(i),(rho(i)-rho(0))/(rho(jj)-rho(0))
        enddo
        enddo
        close(22)
        close(22)
        if(eos .eq. 0) then
        open(unit=21,file=entropy,form='formatted',status='unknown')
        dsus = 0
        dsTs = 0
        do i = 2,jj-2,2
        dsu(i) = 4.d0*eta(i)*((u(i+2)-u(i-2))/(2.d0*deltax))**2*deltax
        & /(3.d0*T(i))/(rho(i)*u(i))
        dsus = dsus + dsu(i)
        dsT(i) =-kappa*((T(i+2)-2.d0*T(i)+T(i-2))/(deltax**2))*deltax
    & /T(i)/(rho(i)*u(i))
        dsT(i) =((q(i+2)-q(i-2))/(2.d0*hx))*hx/T(i)/(rho(i)*u(i))
        dsTs = dsTs + dsT(i)
        enddo
        ds = (dsus -dsTs)*R*gama
        entropy(n) = ds
        write (21,'(4f12.5)') dsa, dsus*R*gama,dsTs*R*gama, ds
        close(21)
    do i = 0,jj
    write (* ,'(i4,f12.5)') i,rho(i)
    write (23,'(f12.6)') hx*(float(i)-float(jj)/2.0)
    enddo
        pause
    close(23)
    elseif(eos .ne. 0) then
    dsus = 0
    dsTs = 0
    do i = 2,jj-2,2
    dsu(i) = 4.d0*eta(i)*((u(i+2)-u(i-2))/(2.d0*deltax))**2*deltax
    \& /(3.d0*T(i))/(rho(i)*u(i))
dsus = dsus + dsu(i)
dsT(i) =-kappa*((T(i+2)-2.d0*T(i)+T(i-2))/(deltax**2))*deltax
\& /T(i)/(rho(i)*u(i))
dsT(i) =((q(i+2)-q(i-2))/(2.d0*hx))*hx/T(i)/(rho(i)*u(i))
dsTs = dsTs + dsT(i)
enddo
do i = 2,jj-2,2
dsu(i) = 4.d0*eta(i)*((u(i+2)-u(i))/deltax)**2*(deltax)
\& /(3.d0*T(i))/(rho(i)*u(i))
dsus = dsus + dsu(i)
dsT(i) =-gama*eta(i)/Pr*((T(i+2)-2*T(i)+T(i-2))/((deltax)**2))
\& *(deltax)/T(i)/(rho(i)*u(i))
dsT(i) =((q(i+2)-q(i))/(deltax))*(deltax)/T(i)/(rho(i)*u(i))
dsTs = dsTs + dsT(i)
enddo
ds = (dsus -dsTs)*Cv
entropy(n) = ds
endif

```
```

c output restart
print *,'Write restart file...'
open (unit=44, file='restart.dat', form='formatted',
\& status='unknown')
do i = 0,jj,1 !Zero out variables
write (44,'(i15,6e25.18)') n,rho(i),u(i),P(i),e(i),T(i),eta(i)
enddo
close(44)
c endif
endif
enddo !j-loop
c--------------analytic solution is only available for gas------------
c------------------------analytic solution-----------------------------
print *,'Analytic solution'
open (unit=41,file='shock.dat',form='formatted',status='unknown')
open(unit=21,file='entropy.dat',form='formatted',status='unknown')
if (eos .ne. 3) then
c caculate parameters
c print *,'alpha2=',alpha,' beta=',beta
c1= sqrt(gama*R*Tinf)
! sound speed of
inflow [cm/us]
c print *,'alpha2=',alpha,' beta=',beta
x0=0.*t(1)*((gama+1.0)*u(0)/4.0 + !shock position from landau and
liftshitz pg 358. Why there is a 0. before t(n),besides, is t(n) the
same mean as T(n)?
\& sqrt((gama+1.0)**2*u(0)**2/16.0+ c1**2 ))
c print *,'alpha2=',alpha,' beta=',beta
x0=0.*x0/lambda
c print *,'alpha2=',alpha,' beta=',beta
M1= sqrt(((p(jj)/p(0))*(gama+1.0)+gama-1.0)/(2.d0*gama) )! mach\#
for the stationary shock solution
v1=M1*c1
upstream velocity
alpha=(gama-1.d0)/(gama+1.d0)+2.d0/((gama+1.d0)*M1**2) ! alpha,
asymptote of analytic solution see BSL notes
beta=9.0*(gama+1.0)*sqrt(acos(-1.0)/8.0/gama)/8.0 ! beta,
from transport phonomena book P352
c lambda=3.d0*mu/rho(0)* ! mean free path [cm], use value in
numerical method
c \& dsqrt(dacos(-1.d0)*M1/8.d0/R/T(0))
c bisection method
do i=0,jj-2,2 ! space step through domain and
find the analytic solution psi
xx =-5.0+(5.0+5.0)*float(i)/(float(jj)-1.0) !dimensionless
position

```
```

    xa = 1.0 ! first guess, psi must be
    between xa and xb
xb = alpha ! xb=alpha will always make f>0
c print *,'alpha2=',alpha,' beta=',beta
c print *,'psialpha3',alpha
c pause
fa = 1.0-xa-(xa-alpha)**alpha ! analytic
solution at xa
\& *exp(beta*M1*(1.0-alpha)*(xx-x0))
fb = 1.0-xb-(xb-alpha)**alpha ! analytic
solution at xb
\& *exp(beta*M1*(1.0-alpha)*(xx-x0))
print *,'xa and xb',xx,xa,xb,fa,fb
if (fa .eq. 0.0) then ! xa first
guess was right!
psi(i) = xa
goto 99
elseif (fb .eq. 0.0) then ! xb first
guess was right!
psi(i) = xb
goto 99
endif
if (fa*fb .ge. 0) pause'root must be bracketed'!determine
interval limits
if (fa.lt. 0) then !orient the search to
keep fa<0
dx=xb-xa
xa=xa
else
dx=xa-xb
xa=xb
endif
print *,'alpha5=',alpha,' beta=',beta
print *,xa,xb,fa,fb
do iter=1,1000 ! iterate bisection method to find psi
at each r position
c print *,iter,'alpha6=',alpha,' beta=',beta
dx=dx*0.5
xb=xa+dx
fb=1.0-xb-(xb-alpha)**alpha
\& *exp(beta*M1*(1.0-alpha)*(xx-x0))
print *,iter,xx,xa,xb,dx,fb
if (fb .le. 0) xa=xb
c print *,iter,'alpha6=',alpha,' beta=',beta
c if(fb .eq. 0) return
enddo
c print *,'out of loop',j
psi(i)=xb
99 continue ! solution converged
c pause

```
```

    write(41,'(I5,10e13.4)')
    \& i,xx,psi(i),
\& (1.0/psi(i)-rho(0))/(rho(jj)-rho(0)),
\& hx*(dfloat(i)-dfloat(jj)/2.d0)/2.0d0,
\& u(i)*c1/v1,v1/u(i)/c1,
\& (rho(i)-rho(0))/(rho(jj)-rho(0)),
\& q(i), PI(i)
enddo
print *,Pr, gama, mu, R, Tinf, rhoinf, cinf,lambda,eta(0)
print *, kappa0,eta(0)/((gama-1.d0)*Pr)
pause
else
do i = 0,jj
write(41,'(I5,4e13.4)')
\& i,
\& hx*(dfloat(i)-dfloat(jj)/2.d0)/2.0d0,
\& (rho(i)-rho(0))/(rho(jj)-rho(0)),
\& p(i)*Pless/(1.d9)
enddo
endif
write(21,'(f12.5)') dsa
do counter = 0, n, 10000
write(21,'(f12.5)') entropy(counter)
enddo
end

```
```

