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Configuration Space Analysis and Synthesis of Planar Variable Kinematic Joints

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Abstract

This paper presents a new approach to the analysis and synthesis of planar variable kinematic joints using a configuration space approach. The advantage of this approach is that the configuration space representation contains both the joint topology and the configuration variables. Based on the same configuration space, different combinations of higher pair equivalent revolute and prismatic joints can be used to analyze and synthesize planar variable kinematic joints. Two practical examples will be presented to illustrate the proposed method.

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